

Random Obstacle Problems

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Chapter 1: Introduction

A course in 8 chapters:

- ▶ Introduction
- ▶ The reflecting Brownian motion
- ▶ Bessel processes
- ▶ The stochastic heat equation
- ▶ Obstacle problems
- ▶ Integration by Parts Formulae
- ▶ The contact set
- ▶ Convergence and Dirichlet Forms

A course in 8 chapters:

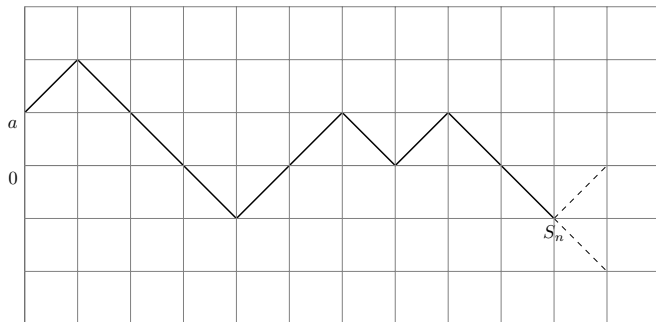
- ▶ Introduction
- ▶ The reflecting Brownian motion
- ▶ Bessel processes
- ▶ The stochastic heat equation
- ▶ Obstacle problems
- ▶ Integration by Parts Formulae
- ▶ The contact set
- ▶ **Open problems**

Symmetric simple random walk

$(Y_i)_{i \geq 1}$ i.i.d. sequence with $\mathbb{P}(Y_i = 1) = \mathbb{P}(Y_i = -1) = 1/2$

$$S_0 := a \in \mathbb{Z}, \quad S_{n+1} = S_n + Y_{n+1},$$

$(S_n)_{n \geq 0}$ defines a Markov chain with values in \mathbb{Z} .



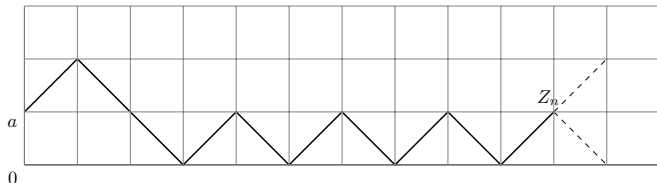
Absolute value of the SSRW

Let $Z_n := |S_n|$, with $S_0 = a \geq 0$. Although this is not obvious at first sight, $(Z_n)_{n \geq 0}$ is also a Markov chain:

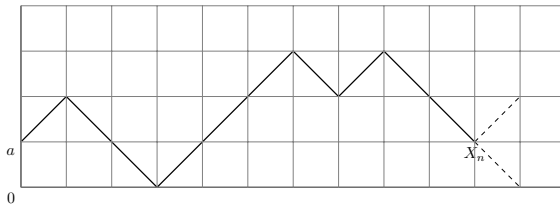
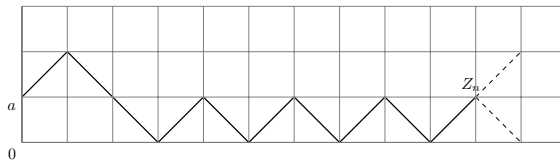
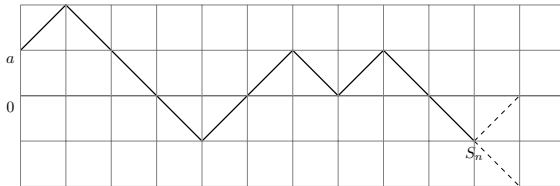
$$Z_{n+1} = \begin{cases} Z_n + W_{n+1} & \text{if } Z_n > 0 \\ 1 & \text{if } Z_n = 0, \end{cases}$$

where $W_{n+1} := Y_{n+1}(\mathbb{1}_{S_n \geq 0} - \mathbb{1}_{S_n < 0})$.

It is easy to see that $(W_i)_{i \geq 1}$ is a copy of $(Y_i)_{i \geq 1}$ and then $(Z_n)_{n \geq 0}$ and $(X_n)_{n \geq 0}$ (for the same fixed a) **have the same law**.



S, Z, X



Discrete interfaces

We define now a Markov chain with values in discrete paths. We fix $N \in \mathbb{N}$ and we define the state space

$$E_N := \{w \in \mathbb{Z}^{2N} : w(0) = w(2N) = 0, \\ |w(i) - w(i-1)| = 1, \forall i = 1, \dots, 2N\}.$$

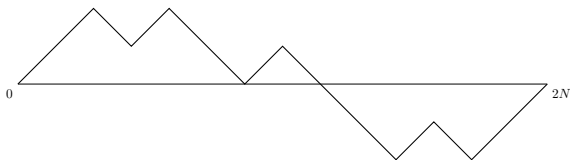
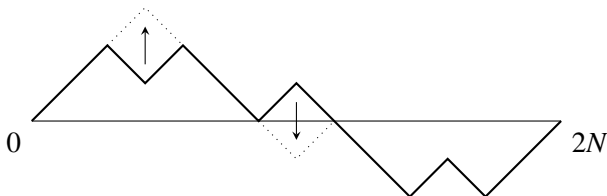


Figure : A typical path in E_N

The free evolution

Then we define a Markov chain with values in E_N as follows: we define a map $F : E_N \times \{1, \dots, 2N - 1\} \rightarrow E_N$, $F(w, j) = \hat{w} \in E_N$, where

$$\hat{w}_i = \begin{cases} w_i + 2 & \text{if } i = j \text{ and } w_{i-1} = w_{i+1} > w_i \\ w_i - 2 & \text{if } i = j \text{ and } w_{i-1} = w_{i+1} < w_i \\ w_i & \text{otherwise.} \end{cases}$$



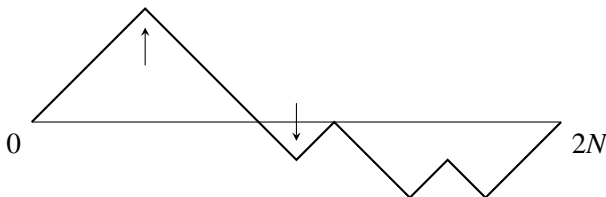
We let $(U_n)_{n \geq 1}$ be an i.i.d. sequence of uniform random variables on $\{1, \dots, 2N - 1\}$; then

$$e_{n+1} := F(e_n, U_{n+1}), \quad e_0 \in E_N.$$

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$$e_{n+1} := F(e_n, U_{n+1}), \quad e_0 \in E_N.$$

The free evolution

We denote the transition matrix of $(e_n)_{n \geq 0}$ by

$$P(x, y) = \mathbb{P}(F(x, U_1) = y).$$

It is easy to see that $P(x, y) = P(y, x)$ and therefore the uniform measure on E_N is invariant and reversible for P .

This is in fact the unique probability invariant measure of $(e_n)_{n \geq 0}$ by the following

Lemma

The Markov chain $(e_n)_{n \geq 0}$ is aperiodic and irreducible.

The free evolution

Proof.

Equivalence with a particle system:

$$E_N \ni w \longleftrightarrow (w_i - w_{i-1})_{i=1, \dots, 2N} \in \{1, -1\}^{2N} \longleftrightarrow \{\bullet, \circ\}^{2N}$$

$$E_N \longleftrightarrow C_N := \{c \in \{\bullet, \circ\}^{2N} : \#\bullet = \#\circ = N\}.$$

$P(x, x') > 0$ iff

$$x \longleftrightarrow \cdots | \bullet | \circ | \cdots, \quad x' \longleftrightarrow \cdots | \circ | \bullet | \cdots$$

or viceversa.

Let $c_0 := |\bullet| \cdots |\bullet| \circ | \cdots | \circ| \in C_N$. From any $c \in C_N$ we can reach c_0 with finitely many transitions having positive probability by moving all particles in c to the left starting with the leftmost one. By symmetry one can go from c_0 to any $c \in C_N$. Aperiodicity: $P(c_0, c_0) > 0$. \square

The reflected interface

Let us now add reflection to our discrete interface. We set

$$E_N^+ := \{w \in E_N : w(i) \geq 0, \forall i = 0, \dots, 2N\}.$$

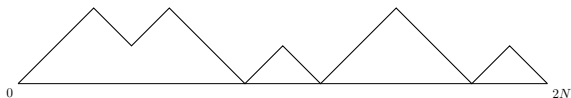
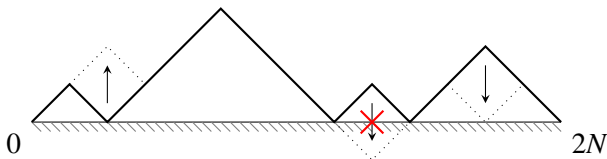


Figure : A typical path in E_N^+

Reflection means now suppression of transitions which would let e_n^+ take negative values:



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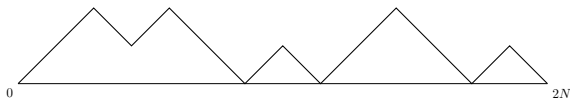
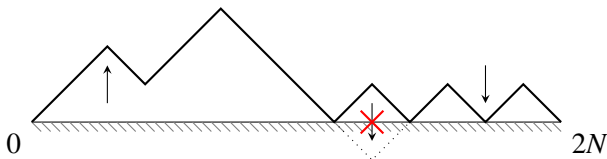


Figure : A typical path in E_N^+

Reflection means now suppression of transitions which would let e_n^+ take negative values:



The reflected interface

The Markov evolution in E_N^+ is defined as follows:

$$F^+ : E_N^+ \times \{1, \dots, 2N - 1\} \rightarrow E_N^+$$

$$F^+(w, j) = \begin{cases} F(w, j) & \text{if } F(w, j) \in E_N^+ \\ w & \text{otherwise.} \end{cases}$$

Then our E_N^+ -valued Markov chain $(e_n^+)_{n \geq 0}$ is defined by

$$e_{n+1}^+ := F^+(e_n^+, U_{n+1}), \quad e_0^+ \in E_N^+.$$

Lemma

The Markov chain $(e_n^+)_{n \geq 0}$ is aperiodic irreducible and has a unique invariant probability measure, given by the uniform probability measure on E_N^+ . This probability measure is furthermore reversible for $(e_n^+)_{n \geq 0}$.

The reflected interface

Proof.

We recall that the transition matrix P of $(e_n)_{n \geq 0}$ is symmetric. Now we have for $x, y \in E_N^+$:

$$P_+(x, y) = \mathbb{P}(f_+(x, U_1) = y) = P(x, y) + P(x, E_N \setminus E_N^+) \mathbb{1}_{(y=x)}.$$

Then P_+ is also symmetric and therefore the uniform measure on E_N^+ is invariant and reversible for P_+ .

$E_N^+ \longleftrightarrow C_N^+$, set of $c \in C_N$ such that for all $k \in \{1, \dots, 2N\}$ the first k sites contain at least $s(k)$ particles, where $s(2i) := i$, $s(2i+1) := i+1$.

Then $c_0 = |\bullet| \cdots |\bullet| \circ | \cdots | \circ | \in C_N^+$ and we can find a path in C_N^+ from any $c \in C_N^+$ to c_0 by moving particles leftwards starting with the leftmost one. Finally $P_+(c_0, c_0) > 0$, so that this Markov chain is aperiodic. □

An important remark

We see that the **reflection** for the dynamics is equivalent to a **conditioning** for the invariant measure.

Let $|e_n|$ be the absolute value of the free interface $(e_n)_{n \geq 0}$. If $(e_n)_{n \geq 0}$ is stationary then the distribution of $|e_0|$ is a probability measure on E_N^+

$$\mathbb{P}(|e_0| = w) \propto \#\{w' \in E_N : |w'| = w\} = 2^{L(w)},$$

$$L(w) := \sum_{i=1}^{2N} \mathbb{1}_{(w_i=0)}, \quad w \in E_N^+.$$

In other words $L(w)$ is the number of excursions of w .

On the other hand, if $(e_n^+)_{n \geq 0}$ is stationary then the law of e_0^+ is uniform on E_N^+ , so that e_0^+ and $|e_0|$ have different laws.

Moreover $(|e_n|)_{n \geq 0}$ is **not Markovian**.

Scaling limits

Let $(S_n)_{n \geq 0}$ be the SSRW with $S_0 := 0$ and

$$B_t^N := \frac{1}{\sqrt{N}} S_{\lfloor Nt \rfloor}, \quad t \geq 0.$$

By Donsker's theorem $(B_t^N)_{t \geq 0} \Longrightarrow (B_t)_{t \geq 0}$ as $N \rightarrow +\infty$.

Under the same scaling the reflecting SSRW $(X_n)_{n \geq 0}$ converges to the reflecting Brownian motion $(\rho_t)_{t \geq 0}$ (see chapter 2).

This process is given by a stochastic differential equation

$$d\rho_t = dB_t + dl_t, \quad \rho_t \geq 0, \quad dl_t \geq 0, \quad \int_0^\infty \rho_t dl_t = 0,$$

- ▶ $t \mapsto (\rho_t, l_t)$ is continuous, ρ_t is non-negative
- ▶ $l_0 = 0$, $l_s \leq l_t$ for $s \leq t$
- ▶ $\text{supp}(dl_t) \subset \{t \geq 0 : \rho_t = 0\}$.

The measure dl_t is the **reflection term**: see (1).

Scaling of the free interface

Let us first consider the stationary version of $(e_n)_{n \geq 0}$ and define

$$v_N(t, x) = \frac{1}{\sqrt{2N}} e_{\lfloor 4N^2 t \rfloor}(\lfloor 2Nx \rfloor), \quad t \geq 0, x \in [0, 1].$$

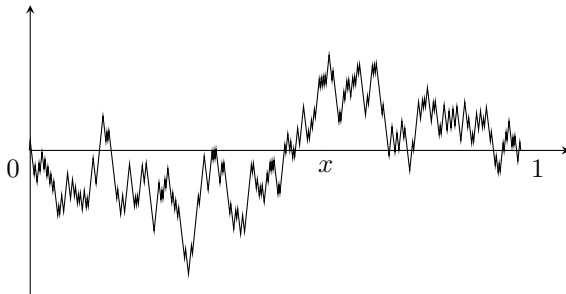


Figure : A typical path of $v_N(t, \cdot)$ for any $t \geq 0$ when N is large

The stochastic heat equation

As $N \rightarrow +\infty$, $v_N \Longrightarrow (v(t, x), t \geq 0, x \in [0, 1])$, that we are going to study in detail in chapter 4 and is a stationary solution to a **stochastic partial differential equation (SPDE)**

$$\left\{ \begin{array}{l} \frac{\partial v}{\partial t} = \frac{1}{2} \frac{\partial^2 v}{\partial x^2} + W, \\ v(t, 0) = v(t, 1) = 0, \quad t \geq 0, \\ v(0, x) = v_0(x), \quad x \in [0, 1]. \end{array} \right.$$

Here W is a **space-time white noise**, a two-parameter version of the derivative of a Brownian motion that we shall define properly later.

Scaling of the reflected interface

Let us now consider the stationary version of $(e_n^+)_{n \geq 0}$ and define

$$u_N(t, x) = \frac{1}{\sqrt{2N}} e_{\lfloor 4N^2 t \rfloor}^+(\lfloor 2Nx \rfloor), \quad t \geq 0, x \in [0, 1].$$

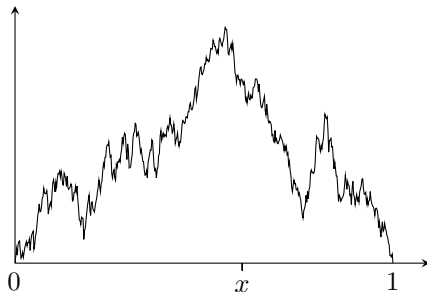


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A SPDE with reflection

As $N \rightarrow +\infty$, $u_N \Longrightarrow (u(t, x), t \geq 0, x \in [0, 1])$, that we are going to study in detail from chapter 5 on and is a stationary solution to a **SPDE with reflection**

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + W + \eta \\ u(0, x) = u_0(x), \quad u(t, 0) = u(t, 1) = 0 \\ u \geq 0, \quad d\eta \geq 0, \quad \int u \, d\eta = 0. \end{array} \right.$$

Here (u, η) is a random pair that consists of

- ▶ a continuous non-negative functions $u(t, x) \geq 0$
- ▶ a Radon measure η on $]0, +\infty[\times]0, 1[$,

such that the support of η is contained in $\{(t, x) : u(t, x) = 0\}$.

The contact set

For all $t \geq 0$ the typical profile of $u(t, \cdot)$ is positive on $]0, 1[$. Where does the reflection act?

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This apparent paradox is solved if we formulate the sentence more precisely: the correct result is that for all $t \geq 0$, a.s. $u(t, \cdot) > 0$ on $]0, 1[$:

$$\forall t > 0, \quad \mathbb{P}(\exists x \in]0, 1[: u(t, x) = 0) = 0.$$

However this does not exclude the existence, with positive probability, of **exceptional** times $t \geq 0$ and $x \in]0, 1[$ such that $u(t, x) = 0$:

$$\mathbb{P}(\exists t > 0, x \in]0, 1[: u(t, x) = 0) > 0.$$

The contact set

The next question is: what can be said about the **contact set**

$$\mathcal{L} := \{(t, x) : t > 0, x \in]0, 1[, u(t, x) = 0\}.$$

After proving that with positive probability u visits 0, one can ask:

- ▶ what is the **typical** behavior at exceptional times $t \geq 0$?
- ▶ That is, if $t > 0$ is such that there exists $x \in]0, 1[$ so that $u(t, x) = 0$, then **how many** such points x exist?

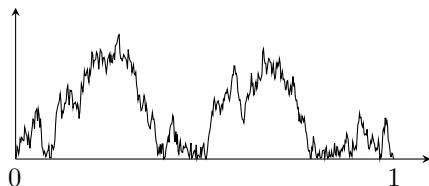


Figure : How many x such that $u(t, x) = 0$: infinitely many?

The contact set

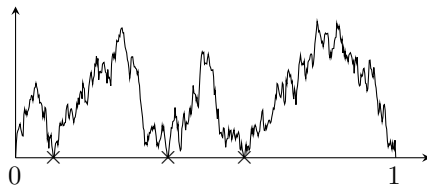


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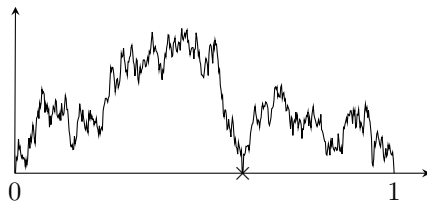


Figure : How many x such that $u(t, x) = 0$: just one? or two? or three?

- ▶ $(u(t, x), t \geq 0, x \in [0, 1])$ has **no standard semi-martingale structure**
- ▶ neither has $(u(t, x), t \geq 0)$
- ▶ which is by the way **not markovian for fixed $x \in [0, 1]$**
- ▶ therefore we must study S(P)DEs **without stochastic calculus**

Difficulties

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The dream is a stochastic calculus for infinite-dimensional processes, following the model of the classical theory (e.g. Revuz-Yor).

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We shall discuss some open problems waiting for someone to solve them.

Chapter 2: The reflecting Brownian motion

Let us meet our first **obstacle problem**.

Lemma (Skorokhod)

Let $y : \mathbb{R}_+ \mapsto \mathbb{R}$ be a continuous function such that $y(0) \geq 0$. Then there exists a unique couple (z, ℓ) of continuous functions on \mathbb{R}_+ s.t.

1. $z = y + \ell$
2. $z \geq 0$
3. $t \mapsto \ell_t$ is monotone non-decreasing, $\ell_0 = 0$, and the support of the associated measure $d\ell_t$ is contained in $\{t \geq 0 : z_t = 0\}$.

Moreover, ℓ and z are given explicitly by

$$\ell_t = \sup_{s \leq t} \max\{-y_s, 0\}, \quad z_t = y_t + \ell_t. \quad (2)$$

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Remark: $\text{supp}(d\ell) \subset \{t \geq 0 : z_t = 0\} \iff \int_0^\infty z_t d\ell_t = 0.$

The Skorokhod Lemma

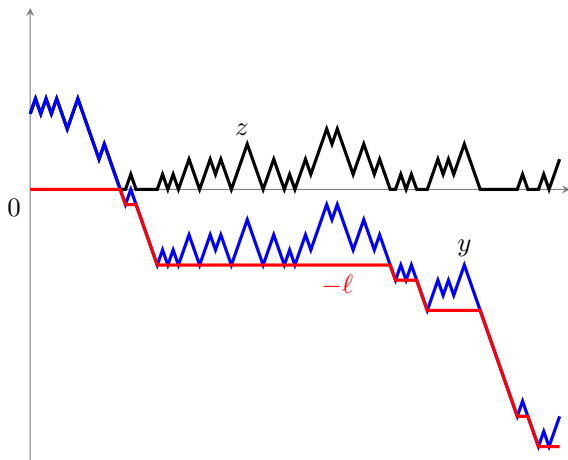


Figure : An example of a triple (y, z, ℓ) from the Skorokhod Lemma.

The Skorokhod Lemma

Proof.

To prove existence, one verifies that $\ell_t := \sup_{s \leq t} \max\{-y_s, 0\}$ and $z := y + \ell$ satisfy the above properties.

If $(\bar{z}, \bar{\ell})$ is another pair with the same properties, then $z - \bar{z} = \ell - \bar{\ell}$ is a continuous function with bounded variation and by the chain rule

$$\begin{aligned} 0 \leq \frac{1}{2}(z_t - \bar{z}_t)^2 &= \int_0^t (z_s - \bar{z}_s) d(\ell_s - \bar{\ell}_s) \\ &= \left[\int_0^t z_s d\ell_s + \int_0^t \bar{z}_s d\bar{\ell}_s - \int_0^t z_s d\bar{\ell}_s - \int_0^t \bar{z}_s d\ell_s \right]. \end{aligned}$$

Since $\text{supp}(d\ell_s) \subset \{s : z_s = 0\}$ and $\text{supp}(d\bar{\ell}_s) \subset \{s : \bar{z}_s = 0\}$, this is equal to

$$- \int_0^t z_s d\bar{\ell}_s - \int_0^t \bar{z}_s d\ell_s \leq 0.$$

Then $(z_t - \bar{z}_t)^2 = (\ell_t - \bar{\ell}_t)^2 = 0$.

ODEs with reflection

Let $f : \mathbb{R} \mapsto \mathbb{R}$ such that

$$|f(x) - f(y)| \leq L|x - y|, \quad x, y \in \mathbb{R}.$$

Proposition

Let $T \geq 0$ and $w \in C([0, T])$ with $w_0 \geq 0$. Then there exists a unique couple $(\rho_t, \ell_t)_{t \in [0, T]}$ of continuous real functions such that

$$\left\{ \begin{array}{l} \rho_t = w_t + \int_0^t f(\rho_s) ds + \ell_t, \quad t \in [0, T] \\ \ell_0 = 0, \\ \rho_t \geq 0, \quad d\ell_t \geq 0, \quad \int_0^T \rho_t d\ell_t = 0. \end{array} \right. \quad (3)$$

Proof.

Let $E_T := C([0, T])$ with norm $\|g\|_L := \sup_{t \in [0, T]} e^{-3Lt} |g_t|$. We define $\Gamma : E_T \mapsto E_T$ by $\Gamma(g) := z$, where (z, ℓ) is the solution of the Skorokhod problem of Lemma 3 associated to y defined by

$$y_t := w_t + \int_0^t f(g_s) ds, \quad t \in [0, T].$$

In particular, $z \geq 0$, $d\ell \geq 0$, $\ell_0 = 0$, and for all $t \in [0, T]$

$$z_t := w_t + \int_0^t f(g_s) ds + \ell_t, \quad \int_0^t z_s d\ell_s = 0.$$

By the explicit representation (2) of (z, ℓ) in terms of y we obtain that Γ is a contraction in E_T and it has a unique fixed point $(\rho_t)_{t \in [0, T]}$. \square

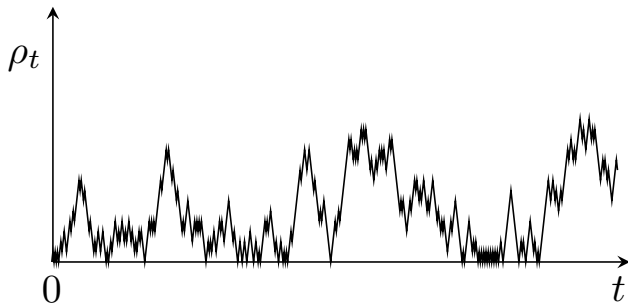
Corollary

Let $(B_t)_{t \geq 0}$ be a standard BM and $x \geq 0$. Then there exists a unique couple $(\rho_t, \ell_t)_{t \geq 0}$ of continuous real processes such that

$$\left\{ \begin{array}{l} \rho_t = x + B_t + \int_0^t f(\rho_s) ds + \ell_t, \quad t \geq 0 \\ \ell_0 = 0, \\ \rho_t \geq 0, \quad d\ell_t \geq 0, \quad \int_0^\infty \rho_t d\ell_t = 0. \end{array} \right. \quad (4)$$

If $f \equiv 0$ we call ρ the **reflecting BM**.

The reflecting BM



H. Tanaka (1979), *Stochastic differential equations with reflecting boundary condition in convex regions*. Hiroshima Math. J. 9, no. 1, 163–177.

Let $D \subset \mathbb{R}^d$ be a convex open bounded domain. We define:

- ▶ For all $x \in \partial D$ a **exposing hyperplane** $H \in \mathcal{H}_x(D)$ is a hyperplane such that D is contained in one of the two half-spaces whose boundary is H and $H \cap \partial D \neq \emptyset$.
- ▶ We call $\hat{n} \in \mathbb{R}^d$ an **inward normal unit vector** at $x \in \partial D$ if $x + \varepsilon \hat{n} \in D$ for some $\varepsilon > 0$, $\|\hat{n}\| = 1$ and \hat{n} is perpendicular to some $H \in \mathcal{H}_x(D)$. We call $\mathcal{N}_x(D)$ the set of all inward unit normal vectors at $x \in \partial D$.

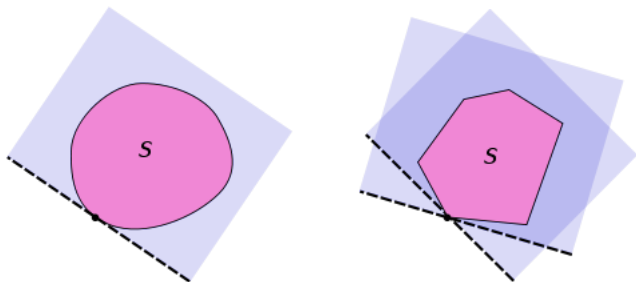


Figure : Exposing hyperplanes

(Special thanks to wikipedia)

Theorem (Tanaka)

For all $w \in C([0, T]; \mathbb{R}^d)$ with $w_0 \in \bar{D}$ there exists a unique pair (ξ, φ) such that

- ▶ $\xi \in C([0, T]; \bar{D})$, $\varphi \in C([0, T]; \mathbb{R}^d)$, $\varphi(0) = 0$, $\xi = w + \varphi$.
- ▶ there exists a monotone non-decreasing $\ell \in C([0, T])$ such that

$$\varphi_t = \int_0^t \mathbb{1}_{(\xi_s \in \partial D)} \mathbf{n}_s \, d\ell_s, \quad t \in [0, T]$$

where $\mathbf{n}_s \in \mathcal{N}_{\xi_s}(D)$ for $d\ell$ -a.e. s .

Moreover the map $w \mapsto \xi$ is continuous in the sup-topology.

One can write the equation as a **differential inclusion**

$$d(\xi_t - w_t) \in \mathbb{1}_{(\xi_t \in \partial D)} \mathcal{N}_{\xi_t}(D) \, d\ell_t, \quad \int_0^\cdot \mathbb{1}_{(\xi_s \in D)} \, d\ell_s = 0.$$

Proof of Uniqueness

Let (ξ, φ) and $(\bar{\xi}, \bar{\varphi})$ be two solutions. Then

$$d\|\xi_t - \bar{\xi}_t\|^2 = (\xi_t - \bar{\xi}_t) \cdot (d\varphi_t - d\bar{\varphi}_t).$$

Now for $d\ell$ -a.e. t

$$(\xi_t - \bar{\xi}_t) \cdot d\varphi_t = \mathbb{1}_{(\xi_s \in \partial D)} (\xi_t - \bar{\xi}_t) \cdot \mathbf{n}_t d\ell_t.$$

Since $\bar{\xi}_t \in \bar{D}$ and $\mathbf{n}_t \in \mathcal{N}_{\xi_t}(D)$, then

$$(\xi_t - \bar{\xi}_t) \cdot \mathbf{n}_t = -(\bar{\xi}_t - \xi_t) \cdot \mathbf{n}_t \leq 0.$$

By symmetry we conclude that $\|\xi_t - \bar{\xi}_t\|^2 \equiv 0$. □

Another approach to reflection: Penalisation

Let $n \geq 1$, $w \in C([0, T])$ with $w_0 \geq 0$ and

$$\rho_t^n = w_t + n \int_0^t (\rho_s^n)^- ds + \int_0^t f(\rho_s^n) ds, \quad t \in [0, T],$$

$$\text{where} \quad r^- = (r)^- := \max\{-r, 0\}, \quad r \in \mathbb{R}.$$

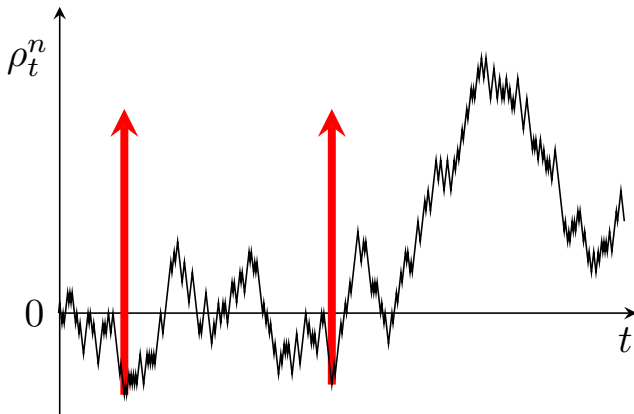
Additive (deterministic!) noise and Lipschitz drift, so clearly pathwise uniqueness and existence of solutions by a Picard iteration.

Proposition

1. *if $n \leq m$ then $\rho_t^n \leq \rho_t^m$ for all $t \in [0, T]$.*
2. *$\rho^n \uparrow \rho$ uniformly on $[0, T]$ as $n \uparrow +\infty$, where $(\rho_t, \ell_t)_{t \geq 0}$ is the unique solution to the equation with reflection (3). Moreover*

$$\lim_{n \uparrow +\infty} n \int_0^t (\rho_s^n)^- ds = \ell_t, \quad t \in [0, T].$$

Penalisation



We set $f_n : \mathbb{R} \mapsto \mathbb{R}$,

$$f_n(x) := nx^- + f(x).$$

Note that f_n is Lipschitz-continuous on \mathbb{R} and satisfies the one-sided estimate:

$$f_n(x) - f_n(y) \leq L(x - y), \quad \forall n \geq 1, x > y.$$

For simplicity we assume that f is monotone non-increasing, so that in particular

$$f_n(x) - f_n(y) \leq 0, \quad \forall n \geq 1, x > y.$$

In the lecture notes you find the argument for the general case.

We call $S(n, w, T) = \rho^n$ the unique solution of

$$\rho_t^n = w_t + \int_0^t f_n(\rho_s^n) ds, \quad t \in [0, T].$$

Step 1 (Monotonicity). We show first that

$\rho^n = S(n, w, T) \leq \rho^m = S(m, w, T)$ if $n \leq m$. Since $f_n(\cdot) \leq f_m(\cdot)$

$$\begin{aligned} \frac{d}{dt} ((\rho^n - \rho^m)^+)^2 &= 2(\rho^n - \rho^m)^+ (f_n(\rho^n) - f_m(\rho^m)) \\ &\leq 2(\rho^n - \rho^m)^+ (f_m(\rho^n) - f_m(\rho^m)) \leq 0. \end{aligned}$$

Since $\rho_0^n = \rho_0^m$, we conclude that $\rho^n \leq \rho^m$. Then

$$S(w, T) := \sup_n S(n, w, T) = \lim_{n \rightarrow +\infty} S(n, w, T)$$

where the supremum and the limit are taken pointwise, i.e. for all $t \in [0, T]$. It is not clear at this point whether $\rho := S(w, T)$ is a continuous function. This will be proved in the next steps.

Step 2 (The case of a smooth obstacle). Let $w \in C^\infty([0, T])$ with $w_0 \geq 0$. Let us fix n . Writing for simplicity $x := \rho^n$

$$\dot{x}_t = f_n(x_t) + \dot{w}_t,$$

$$\begin{aligned} \frac{d}{dt}|x_t - x_{t+h}| &= (f_n(x_t) - f_n(x_{t+h}) + \dot{w}_t - \dot{w}_{t+h}) \operatorname{sign}(x_t - x_{t+h}) \\ &\leq |\dot{w}_t - \dot{w}_{t+h}| \end{aligned}$$

so that

$$|x_t - x_{t+h}| \leq |x_0 - x_h| + \int_0^t |\dot{w}_s - \dot{w}_{s+h}| \, ds.$$

If we divide by $h > 0$ and let $h \downarrow 0$ we obtain

$$\begin{aligned} |\dot{x}_t| &\leq |\dot{x}_0| + \int_0^t |\ddot{w}_s| \, ds \leq |f_n(w_0)| + |\dot{w}_0| + \int_0^t |\ddot{w}_s| \, ds \\ &= |f(x_0)| + |\dot{w}_0| + \int_0^t |\ddot{w}_s| \, ds. \end{aligned}$$

Therefore

$$\sup_{n \geq 1} \sup_{t \in [0, T]} |\dot{x}_t| \leq C = C(T, w).$$

By the Arzelà-Ascoli theorem, the sequence $x = \rho^n = S(n, w, T)$ in $n \geq 1$ is compact in $C([0, T])$. Therefore ρ^n converges uniformly,

$$\ell_t^n := n \int_0^t (\rho_s^n)^- ds = \rho_t^n - w_t - \int_0^t f(\rho_s^n) ds \longrightarrow \ell_t$$

and one shows that (ρ, ℓ) is a solution to the SDE with reflection.

Step 3 (Continuity of the map $w \mapsto S(n, w, T)$ uniformly in n). Let now $w \in C([0, T])$ with $w_0 \geq 0$. We still write $x := \rho^n$ for fixed n . Set

$$y_t := x_t - w_t \implies \dot{y}_t = f_n(x_t). \quad (5)$$

Let $\hat{w} \in C([0, T])$ with $\hat{w}_0 \geq 0$, and set $x = S(n, w, T)$, $\hat{x} = S(n, \hat{w}, T)$. We denote

$$\|g\|_\infty := \sup_{[0, T]} |g_t|, \quad g : [0, T] \mapsto \mathbb{R}.$$

We set y as in (5) and \hat{y} analogously after replacing (x, w) by (\hat{x}, \hat{w}) .

Let $\kappa := \|w - \hat{w}\|_\infty$. Now if $y_t - \hat{y}_t - \kappa > 0$ then

$$\begin{aligned} x_t - \hat{x}_t &> w_t - \hat{w}_t + \kappa \\ &\geq -\|w - \hat{w}\|_\infty + \kappa = 0. \end{aligned}$$

Then since $r \mapsto f_n(r)$ is monotone non-increasing,

$$\frac{d}{dt} ((y_t - \hat{y}_t - \kappa)^+)^2 = 2 (y_t - \hat{y}_t - \kappa)^+ (f_n(x_t) - f_n(\hat{x}_t)) \leq 0.$$

Since $y_0 = \hat{y}_0$, we obtain that $y_t - \hat{y}_t \leq \kappa$ for all $t \in [0, T]$, and by symmetry

$$\|y - \hat{y}\|_\infty \leq \kappa = \|\mathbf{w} - \hat{\mathbf{w}}\|_\infty.$$

By definition $y = x - \mathbf{w}$, so that

$$\|S(n, \mathbf{w}, T) - S(n, \hat{\mathbf{w}}, T)\|_\infty \leq 2\|\mathbf{w} - \hat{\mathbf{w}}\|_\infty.$$

By letting $n \rightarrow +\infty$:

$$\|S(\mathbf{w}, T) - S(\hat{\mathbf{w}}, T)\|_\infty \leq 2\|\mathbf{w} - \hat{\mathbf{w}}\|_\infty.$$

Step 4 (Conclusion).

- ▶ Let $w \in C([0, T])$, $w^m \in C^\infty([0, T])$ such that

$$w_0, w_0^m \geq 0, \quad \lim_{m \rightarrow +\infty} \|w - w^m\|_\infty = 0.$$

- ▶ By Step 2, $S(w^m, T) \in C([0, T])$.
- ▶ By Step 3 $S(w^m, T)$ converges uniformly on $[0, T]$ to $\rho = S(w, T)$, so that $S(w, T) \in C([0, T])$.
- ▶ We can conclude the proof by Dini's Theorem. □

The penalised SDE

For $x \in \mathbb{R}$ and B a standard BM we set

$$\rho_t^n(x) = x + B_t + n \int_0^t (\rho_s^n(x))^- ds + \int_0^t f(\rho_s^n(x)) ds, \quad t \geq 0,$$

The infinitesimal generator of ρ^n is for $\varphi \in C_c^2(\mathbb{R})$

$$L^n \varphi(x) := \frac{1}{2} \varphi''(x) + (nx^- + f(x)) \varphi'(x), \quad x \in \mathbb{R}.$$

Moreover ρ^n admits as reversible invariant measure

$$\mu_n(dx) = e^{-n(x^-)^2 + 2F(x)} dx$$

where $F : \mathbb{R} \mapsto \mathbb{R}$ is any function such that

$$F'(x) = f(x), \quad x \in \mathbb{R}.$$

Note that $\mu_n([-\infty, 0]) < +\infty$ for n large, but $\mu_n([0, +\infty]) \leq +\infty$ in general.

The penalised SDE

Lemma

The measure μ is invariant and reversible for $(\rho_t)_{t \geq 0}$ and

$$\lim_{n \rightarrow +\infty} \int_{\mathbb{R}} \varphi d\mu_n = \int_{\mathbb{R}} \varphi d\mu, \quad \forall \varphi \in C_c(\mathbb{R}),$$

where

$$\mu(dx) := \mathbb{1}_{(x \geq 0)} e^{2F(x)} dx.$$

Here is an important message, that we have already noticed for discrete interfaces:

Remark

A *reflection* for the dynamics means a *conditioning* for the invariant measure.

Since μ_n is reversible for ρ^n , for all $\varphi, \psi \in C_c(\mathbb{R})$

$$\int_{\mathbb{R}} \varphi(x) \mathbb{E}(\psi(\rho_t^n(x))) \mu_n(dx) = \int_{\mathbb{R}} \psi(x) \mathbb{E}(\varphi(\rho_t^n(x))) \mu_n(dx).$$

We see that $\mathbb{1}_{(x \geq 0)} \mu_n(dx) = \mathbb{1}_{(x \geq 0)} \mu(dx)$, while

$$\mu_n(]-\infty, 0[) = \int_{]-\infty, 0[} e^{-nx^2 + 2F(x)} dx \rightarrow 0$$

as $n \rightarrow +\infty$. We conclude by dominated convergence □

A useful formula

Lemma

Let $(\rho_t, \ell_t)_{t \geq 0}$ be the solution to the SDE with reflection (4). Then

$$\int_{\mathbb{R}_+} e^{2F(x)} \mathbb{E}(\ell_t(x)) \, dx = \frac{t}{2} e^{2F(0)}, \quad t \geq 0. \quad (6)$$

Proof. We use the notation

$$\ell_t^n(x) := \int_0^t n (\rho_s^n(x))^- \, ds.$$

We are going to prove two formulae:

$$\lim_{n \rightarrow +\infty} \int_{\mathbb{R}} \mu_n(dx) \mathbb{E}(\ell_t^n(x)) = \int_{\mathbb{R}_+} \mu(dx) \mathbb{E}(\ell_t(x)), \quad (7)$$

$$\lim_{n \rightarrow +\infty} \int_{\mathbb{R}} \mu_n(dx) \mathbb{E}(\ell_t^n(x)) = \frac{t}{2} e^{2F(0)}. \quad (8)$$

Again, for simplicity we assume that f is monotone non-increasing. In the lecture notes you find the argument for the general case.

First, since μ_n is invariant for ρ^n ,

$$\int_{\mathbb{R}} \mu_n(dx) \mathbb{E} \left(\int_0^t n (\rho_s^n(x))^- ds \right) = t \int_{\mathbb{R}} \mu_n(dx) n x^-$$

and by a simple change of variable this is equal to

$$t \int_{\mathbb{R}} e^{-x^2 + 2F(n^{-1/2}x)} x^- dx \rightarrow t e^{2F(0)} \int_{\mathbb{R}} e^{-x^2} x^- dx = \frac{t}{2} e^{2F(0)} \quad (9)$$

as $n \rightarrow +\infty$. In the above limit we can use dominated convergence since for $x \leq 0$

$$\begin{aligned} F(x) &= - \int_x^0 f(y) dy + F(0) \leq - \int_x^0 f(0) dy + F(0) \\ &= -f(0)x + F(0) \leq C(|x| + 1) \end{aligned}$$

for some $C > 0$. We have therefore proved (8). We must now prove (7).

Since f is monotone non-increasing

$$\ell_t^n = \int_0^t n (\rho_s^n(x))^- ds = \rho_t^n - B_t - x - \int_0^t f(\rho_s^n) ds$$

becomes monotone non-decreasing in n .

This result is not so trivial, since $n \mapsto (\rho_s^n)^-$ is monotone non-increasing.

Let us now use the notation

$$\begin{aligned} G_n(x) &:= \mathbb{E}(\ell_t^n(x)) = \int_0^t \mathbb{E}(n (\rho_s^n(x))^-) ds \\ &= \mathbb{E}(\rho_t^n(x)) - x - \int_0^t \mathbb{E}(f(\rho_s^n(x))) ds, \\ G(x) &:= \mathbb{E}(\ell_t(x)). \end{aligned}$$

By the convergence of the penalisation procedure, by monotone convergence and since $\mathbb{1}_{(x \geq 0)} \mu_n(dx) = \mu(dx)$, as $n \uparrow +\infty$

$$\int_{\mathbb{R}_+} G_n(x) \mu_n(dx) = \int_{\mathbb{R}_+} G_n(x) \mu(dx) \uparrow \int_{\mathbb{R}_+} \mu(dx) G(x).$$

For all $x \leq 0$ we have $\rho_t^n(x) \leq \rho_t^n(0)$ and $\rho_t^n(0) \leq \rho_t(0)$. Then

$$G_n(x) \leq \mathbb{E}(\rho_t(0)) - x - \int_0^t \mathbb{E}(f(\rho_s(0))) ds =: C_t - x,$$

for all $x \leq 0$ and therefore as $n \uparrow +\infty$

$$\begin{aligned} 0 &\leq \int_{\mathbb{R}_-} G_n(x) \mu_n(dx) = \int_{\mathbb{R}_-} G_n(x) e^{-nx^2+2F(x)} dx \\ &\leq \int_{\mathbb{R}_-} (C_t - x) e^{-nx^2+2C(x^2+1)} dx \downarrow 0. \end{aligned}$$

We have thus proved (7).

Theorem

Let $(X_t)_{t \geq 0}$ be a real-valued continuous semimartingale with quadratic variation $(\langle X \rangle_t)_{t \geq 0}$. There exists a measurable process $(L_t^a)_{t \geq 0, a \in \mathbb{R}}$ such that a.s. for all bounded Borel $\varphi : \mathbb{R} \mapsto \mathbb{R}$

$$\int_0^t \varphi(X_s) d\langle X \rangle_s = \int_{\mathbb{R}} \varphi(a) L_t^a da, \quad t \geq 0. \quad (10)$$

The process $(L_t^a)_{t \geq 0, a \in \mathbb{R}}$ has a modification such that a.s. $(t, a) \mapsto L_t^a$ is continuous in t and cadlag in a .

The process $(L_t^a)_{t \geq 0}$ is called the **local time** of X at $a \in \mathbb{R}$ and (10) is known as the **occupation time formula**.

For all $a \in \mathbb{R}$ the process $(L_t^a)_{t \geq 0}$ is monotone non-decreasing and the measure dL_t^a is supported by $\{t \geq 0 : X_t = a\}$.

Proposition (Tanaka's formula)

For all $a \in \mathbb{R}$ and $t \geq 0$

$$|X_t - a| = |X_0 - a| + \int_0^t \operatorname{sgn}(X_s - a) dX_s + L_t^a$$
$$(X_t - a)^+ = (X_0 - a)^+ + \int_0^t \mathbb{1}_{(X_s > a)} dX_s + \frac{1}{2} L_t^a$$

where $\operatorname{sgn}(x) := \mathbb{1}_{(x > 0)} - \mathbb{1}_{(x \leq 0)}$.

The solution $(\rho_t)_{t \geq 0}$ to the reflected SDE (4) is a continuous semimartingale. By Tanaka's formula applied to $(\rho_t)^+ = \rho_t$

$$\ell_t = \frac{1}{2} L_t^0 \quad t \geq 0, \text{ a.s.}$$

In particular, a.s. ℓ_t is adapted to the filtration of ρ .

All this is not true for generic w in the Skorokhod Lemma. Let us give two instructive and simple examples for $f \equiv 0$:

1. if $w \equiv 0$, then $\rho \equiv 0$ and $\ell \equiv 0$.
2. if $\hat{w}_t = -t$, then $\hat{\ell}_t = t$ and $\hat{\rho}_t = 0$, $t \in [0, T]$.

Then

$$\rho = \hat{\rho} = 0, \quad \ell = 0, \quad \hat{\ell}_t = t.$$

The same amount of time spent at 0 is associated with different values of the reflection process.

Moreover ℓ , though always an explicit function of w by the Skorokhod Lemma 3, may not be a function of ρ : indeed $\rho = \hat{\rho}$ but $\ell \neq \hat{\ell}$.

Finally neither ρ nor $\hat{\rho}$ have local times.

The explicit law of RBM

Proposition

Let $(\rho_t)_{t \geq 0}$ be a reflecting Brownian motion started at $x \geq 0$ and $(B_t)_{t \geq 0}$ a standard Brownian motion in \mathbb{R} . Then $(\rho_t)_{t \geq 0}$ and $(|x + B_t|)_{t \geq 0}$ have the same law.

Proof.

By Tanaka's formula (see Proposition 12)

$$|x + B_t| = x + \int_0^t \text{sign}(x + B_s) dB_s + L_t^{-x}, \quad t \geq 0,$$

The process $\beta_t := \int_0^t \text{sign}(x + B_s) dB_s$ is a standard BM by Lévy's characterisation theorem. By the Skorokhod lemma

$$L_t^{-x} = \sup_{s \leq t} \max\{-x - \beta_s, 0\}, \quad |x + B| = x + \beta + L^{-x},$$

and therefore $(\rho_t)_{t \geq 0} = \Gamma(B)$ and $(|x + B_t|)_{t \geq 0} = \Gamma(\beta)$.

Results on the contact set

In particular $\{t \geq 0 : \rho_t = 0\}$ and $\mathcal{Z} := \{t \geq 0 : B_t = 0\}$ **have the same law** (for simplicity $x = 0$ here).

- ▶ a.s. \mathcal{Z} is closed, unbounded, without isolated points and has zero Lebesgue measure.
- ▶ Let $(L_t)_{t \geq 0}$ be the local time at 0 of B and

$$\tau_t := \inf\{s > 0 : L_s > t\}, \quad t \geq 0.$$

Then $(\tau_t)_{t \geq 0}$ is a stable subordinator of index $1/2$.

- ▶ The set \mathcal{Z} is a.s. the closure of the image of $(\tau_t)_{t \geq 0}$: a **regenerative set**.
- ▶ The Hausdorff dimension of \mathcal{Z} is a.s. equal to $1/2$.

Chapter 3: Bessel processes

δ -Bessel processes are solutions $(\rho_t)_{t \geq 0}$ to the SDE

$$\rho_t = x + \frac{\delta - 1}{2} \int_0^t \rho_s^{-1} ds + B_t, \quad \rho_t \geq 0, \quad t \geq 0, \quad (11)$$

where $(B_t)_{t \geq 0}$ is a BM, $x \geq 0$, and $\delta > 1$. For $\delta = 1$ the equation is

$$\rho_t = x + \ell_t + B_t, \quad \ell_0 = 0, \quad d\ell \geq 0, \quad \int_0^t \rho_s d\ell_s = 0. \quad (12)$$

This is the reflecting Brownian motion. For all $\delta \geq 1$, the law of the δ -Bessel process is \mathbf{P}_x^δ .

- ▶ $X_t : C([0, +\infty[) \mapsto \mathbb{R}$ is the canonical process, $X_t(w) := w_t, t \geq 0$
- ▶ $\mathcal{F}_t^0 := \sigma(X_s, s \in [0, t])$ is the canonical filtration
- ▶ let \mathbf{W}_x be the law of $(x + B_t)_{t \geq 0}$.

Existence and uniqueness

Let $g :]0, +\infty[\mapsto \mathbb{R}$ be continuous and monotone non-increasing such that g is Lipschitz-continuous on $[\varepsilon, +\infty[$ for all $\varepsilon > 0$.

We allow $g(x)$ to blow up as $x \downarrow 0$. The main example we have in mind is $g(x) = Cx^{-\alpha}$, $\alpha > 0$, $C > 0$.

Proposition

Let $w \in C([0, T])$ with $w_0 \geq 0$ and $g :]0, +\infty[\mapsto \mathbb{R}$ as above. Then there exists a unique couple $(\rho, \ell) \in (C([0, T]))^2$ such that

$$\rho \geq 0, \quad g \circ \rho \in L^1(0, T), \quad \ell_0 = 0, \quad d\ell \geq 0, \quad \rho d\ell = 0$$

$$\rho_t = w_t + \int_0^t g(\rho_s) ds + \ell_t, \quad t \in [0, T].$$

Let us start with uniqueness. If (ρ, ℓ) and $(\hat{\rho}, \hat{\ell})$ are two solutions, then

$$\rho_t - \hat{\rho}_t = \int_0^t (g(\rho_s) - g(\hat{\rho}_s)) \, ds + \ell_t - \hat{\ell}_t,$$

i.e. $\rho - \hat{\rho}$ is continuous with bounded variation on $[0, T]$. Therefore by the chain rule

$$d(\rho_t - \hat{\rho}_t)^2 = 2(\rho_t - \hat{\rho}_t) \left[(g(\rho_t) - g(\hat{\rho}_t)) \, dt + d\ell_t - d\hat{\ell}_t \right] \leq 0$$

and this proves uniqueness.

Let us show now existence. Let us set

$$A_\varepsilon(x) := g(\varepsilon + x^+), \quad x \in \mathbb{R},$$

where $\varepsilon > 0$ is fixed and $x^+ := \max\{x, 0\}$. Note that A_ε is Lipschitz-continuous and monotone non-increasing, i.e.

$$A_\varepsilon(x) - A_\varepsilon(y) \leq 0, \quad \forall \varepsilon > 0, x > y.$$

There is a unique continuous solution $(\rho^\varepsilon, \ell^\varepsilon)$ to

$$\rho_t^\varepsilon = w_t + \int_0^t A_\varepsilon(\rho_s^\varepsilon) ds + \ell_t^\varepsilon, \quad t \in [0, T],$$

with the usual conditions $\rho^\varepsilon \geq 0$, $d\ell^\varepsilon \geq 0$, $\rho^\varepsilon d\ell^\varepsilon = 0$.

Now, $\varepsilon \mapsto A_\varepsilon(x)$ is monotone non-increasing since $g(\cdot)$ is, and we expect $\varepsilon \mapsto \rho^\varepsilon$ to be also monotone non-increasing. Indeed, let $\varepsilon > \varepsilon' > 0$. Then

$$\begin{aligned} & \mathbb{d} \left(\left(\rho_t^\varepsilon - \rho_t^{\varepsilon'} \right)^+ \right)^2 \\ &= 2 \left(\rho_t^\varepsilon - \rho_t^{\varepsilon'} \right)^+ \left((A_\varepsilon(\rho_t^\varepsilon) - A_{\varepsilon'}(\rho_t^{\varepsilon'})) dt + d\ell_t^\varepsilon - d\ell_t^{\varepsilon'} \right) \\ &\leq 2 \left(\rho_t^\varepsilon - \rho_t^{\varepsilon'} \right)^+ \left((A_{\varepsilon'}(\rho_t^\varepsilon) - A_{\varepsilon'}(\rho_t^{\varepsilon'})) dt + d\ell_t^\varepsilon - d\ell_t^{\varepsilon'} \right) \leq 0 \end{aligned}$$

- ▶ the first inequality: monotonicity of $\varepsilon \mapsto A_\varepsilon$
- ▶ the second: monotonicity of $A_\varepsilon(\cdot)$ and

$$\rho_t^\varepsilon > \rho_t^{\varepsilon'} \geq 0 \implies d\ell_t^\varepsilon = 0 \text{ and } -d\ell_t^{\varepsilon'} \leq 0.$$

Therefore

$$\rho^\varepsilon \leq \rho^{\varepsilon'}, \quad \forall \varepsilon > \varepsilon' > 0,$$

i.e. $\varepsilon \mapsto \rho^\varepsilon$ is monotone **non-increasing**.

Note now that $\gamma^\varepsilon := \varepsilon + \rho^\varepsilon$ satisfies

$$\gamma_t^\varepsilon = \varepsilon + w_t + \int_0^t g(\gamma_s^\varepsilon) ds + \ell_t^\varepsilon, \quad t \in [0, T],$$

with $\gamma^\varepsilon \geq \varepsilon$, $d\ell^\varepsilon \geq 0$, $(\gamma^\varepsilon - \varepsilon) d\ell^\varepsilon = 0$. In other words, γ^ε is the solution to a SDE with reflection at level ε , a Lipschitz non-linearity $g(\cdot \vee \varepsilon)$ and driving function $\varepsilon + w$; and we expect $\varepsilon \mapsto \gamma^\varepsilon$ to be monotone non-decreasing. Indeed, let $\varepsilon > \varepsilon' > 0$. Then

$$\begin{aligned} d \left(\left(\gamma_t^{\varepsilon'} - \gamma_t^\varepsilon \right)^+ \right)^2 &= \\ &= 2 \left(\gamma_t^{\varepsilon'} - \gamma_t^\varepsilon \right)^+ \left((g(\gamma_t^{\varepsilon'}) - g(\gamma_t^\varepsilon)) dt + d\ell_t^{\varepsilon'} - d\ell_t^\varepsilon \right) \leq 0 \end{aligned}$$

which implies that

$$\varepsilon + \rho^\varepsilon = \gamma^\varepsilon \geq \gamma^{\varepsilon'} = \varepsilon' + \rho^{\varepsilon'}, \quad \forall \varepsilon > \varepsilon' > 0,$$

i.e. $\varepsilon \mapsto \varepsilon + \rho^\varepsilon = \gamma^\varepsilon$ is monotone **non-decreasing**.

We obtain $\varepsilon + \rho^\varepsilon \geq \rho^{\varepsilon'} \geq \rho^\varepsilon$ for $\varepsilon > \varepsilon' > 0$, so that (ρ^ε) is a Cauchy family in the sup norm as $\varepsilon \downarrow 0$; we denote the limit by ρ . Moreover by monotone convergence

$$\int_0^t g(\varepsilon + \rho_s^\varepsilon) ds \uparrow \int_0^t g(\rho_s) ds, \quad \varepsilon \downarrow 0.$$

We also obtain that, as $\varepsilon \downarrow 0$,

$$\ell_t^\varepsilon = \rho_t^\varepsilon - w_t - \int_0^t g(\varepsilon + \rho_s^\varepsilon) ds$$

converges to a continuous, monotone non-decreasing function ℓ_t with $\ell_0 = 0$. Since ρ^ε converges uniformly to ρ

$$0 = \int_0^t \rho_s^\varepsilon d\ell_s^\varepsilon \rightarrow \int_0^t \rho_s d\ell_s, \quad t \in [0, T]. \quad \square$$

Theorem

Let $\delta > 1$ and $x \geq 0$ and $(B_t)_{t \geq 0}$ a standard BM. Then the equation defining the δ -Bessel process enjoys pathwise uniqueness and existence of strong solutions.

Proof. Let us set $g(x) := \frac{\delta-1}{2} x^{-1}$, $x > 0$. By the Proposition, a.s. there exists a unique couple $(\rho, \ell) \in (C([0, T]))^2$ such that $\rho \geq 0$, $\rho^{-1} \in L^1(0, T)$, $\ell_0 = 0$, $d\ell \geq 0$, $\rho d\ell = 0$ and

$$\rho_t = x + B_t + \frac{\delta-1}{2} \int_0^t \rho_s^{-1} ds + \ell_t, \quad t \in [0, T]. \quad (13)$$

By Proposition 14 if (ρ, ℓ) and $(\hat{\rho}, \hat{\ell})$ with $\ell = \hat{\ell} \equiv 0$ satisfy (13), then $\rho \equiv \hat{\rho}$, which proves pathwise uniqueness for (11).

We must now prove that the solution (ρ, ℓ) satisfies a.s. $\ell \equiv 0$. Let

$$\rho_t^\varepsilon = w_t + \int_0^t f_\varepsilon(\rho_s^\varepsilon) ds + \ell_t^\varepsilon,$$

$$f_\varepsilon(x) := \frac{\delta - 1}{2}(\varepsilon + x)^{-1}, \quad F_\varepsilon(x) = \frac{\delta - 1}{2} \log(\varepsilon + x).$$

We use (6) with $e^{2F_\varepsilon(x)} = (\varepsilon + x)^{\delta-1}$ and obtain

$$\int_{\mathbb{R}_+} (\varepsilon + x)^{\delta-1} \mathbb{E}(\ell_t^\varepsilon(x)) dx = \frac{t}{2} \varepsilon^{\delta-1}.$$

As $\varepsilon \downarrow 0$ we obtain

$$\int_{\mathbb{R}_+} x^{\delta-1} \mathbb{E}(\ell_t(x)) dx = 0.$$

Since $\mathbb{R}_+ \ni x \mapsto \mathbb{E}(\ell_t(x))$ is a monotone non-increasing function, we obtain that $\mathbb{E}(\ell_t(x)) = 0$ for all $x > 0$ and all $t \geq 0$. In order to prove that $\mathbb{E}(\ell_t(0)) = 0$, we can show that a.s. $\mathbb{R}_+ \ni x \mapsto \ell_t(x)$ is continuous.

See the lecture notes.

Squared Bessel Processes

The classical construction of Bessel processes is different: first one defines the δ -**squared Bessel process**, namely the only non-negative solution to the SDE

$$Z_t = y + \delta t + 2 \int_0^t \sqrt{Z_s} dB_s, \quad t \geq 0, \quad (14)$$

where $y, \delta \geq 0$. By the classical Yamada-Watanabe theorem, this equation enjoys pathwise uniqueness, see e.g. [Revuz-Yor, Theorem IX.3.5]. One then defines the δ -Bessel $\rho_t := \sqrt{Z_t}$, and shows with the Ito formula that ρ solves (11) with $x = \sqrt{y}$, at least for $\delta \geq 2$.

With equation (14) one can introduce at once the whole family of δ -Bessel processes with $\delta \geq 0$, while the SDEs (11)-(12) yield the correct process only for $\delta \geq 1$: we shall discuss the case $\delta < 1$ later.

Theorem

Let $T_0 := \inf\{t > 0 : X_t = 0\}$. Fix $\delta \geq 1$. Then we have

1. $\mathbf{P}_x^\delta(T_0 < +\infty) = 1$ for all $x > 0$ iff $\delta < 2$.
2. $\mathbf{P}_x^\delta(T_0 < +\infty) = 0$ for all $x > 0$ iff $\delta \geq 2$.

Proof. By scaling and uniqueness in law, we have the following property for the solution to (11): for all $c > 0$

the law of $(cX_{c^{-2}t})_{t \geq 0}$ under \mathbf{P}_x^δ is given by \mathbf{P}_{cx}^δ ,

namely the δ -Bessel process is **self-similar of index $\frac{1}{2}$** . In particular, $\mathbf{P}_x^\delta(T_0 < +\infty) = \mathbf{P}_1^\delta(T_0 < +\infty)$ for all $x > 0$.

Let $\delta \geq 1$ and $\nu := \frac{\delta}{2} - 1 \geq -\frac{1}{2}$. If we set for $t \geq 0$,

$$A_t := \int_0^t \exp(2(B_s + \nu s)) ds, \quad \tau_t := \inf\{u \geq 0 : A_u > t\},$$

then under \mathbf{P}_1^δ the process $(X_t, t \in [0, T_0])$ has the same law as $(\exp(\xi_{\tau_t}), t \in [0, A_\infty])$, where we set $\xi_t := B_t + \nu t$. This is a particular case of the so-called **Lamperti formula**.

Since $\frac{B_t}{t} \rightarrow 0$ a.s. as $t \rightarrow +\infty$, we obtain that a.s.

$$A_\infty := \int_0^{+\infty} \exp(2(B_s + \nu s)) ds$$

is finite if $\nu < 0$ and it is infinite if $\nu > 0$. For the case $\nu = 0$, see the lecture notes. □

Another possible proof: via the **scale function** of Bessel processes

$$s(x) := \begin{cases} -x^{2-\delta} & \text{if } \delta > 2 \\ \log x & \text{if } \delta = 2 \\ x^{2-\delta} & \text{if } \delta < 2 \end{cases} \quad x \geq 0,$$

then under \mathbf{P}_x^δ the process $s(X_{t \wedge T_0})_{t \geq 0}$ is a local martingale; moreover, setting and $T_a := \inf\{t \geq 0 : X_t = a\}$, we have

$$\mathbf{P}_x^\delta(T_a < T_b) = \frac{s(b) - s(x)}{s(b) - s(a)}, \quad 0 < a \leq x \leq b.$$

Then letting $a \downarrow 0$ and $b \uparrow +\infty$ for $x > 0$, we find that

$\mathbf{P}_x^\delta(T_0 < +\infty) = 1$ for $\delta < 2$ and $\mathbf{P}_x^\delta(T_0 < +\infty) = 0$ for $\delta \geq 2$. □

Local times at 0 for $\delta \in]1, 2[$

Let $(\mathcal{L}_t^a)_{a,t \geq 0}$ be the local times a δ -Bessel process as a semi-martingale, i.e. in the sense of (10). By Tanaka's formula (see Proposition 12)

$$\rho_t = \rho_t^+ = \rho_0^+ + \int_0^t \mathbb{1}_{(\rho_s > 0)} d\rho_s + \frac{1}{2} \mathcal{L}_t^0 = \rho_0 + \rho_t - \rho_0 + \frac{1}{2} \mathcal{L}_t^0$$

which implies $L_t^0 \equiv 0$. However

$$\ell_t^a := a^{1-\delta} \mathcal{L}_t^a, \quad a > 0, \quad \ell_t^0 := \lim_{a \downarrow 0} \ell_t^a,$$

yields a **bi-continuous** family $(\ell_t^a)_{a,t \geq 0}$ with the occupation-time formula

$$\int_0^t \psi(\rho_s) ds = \int_{\mathbb{R}_+} \psi(a) \ell_t^a a^{\delta-1} da.$$

- ▶ $\tau_t := \inf\{s > 0 : \ell_s^0 > t\}$ is a stable subordinator of index $1 - \frac{\delta}{2}$
- ▶ $\{t \geq 0 : \rho_t = 0\}$ has Hausdorff measure equal to $1 - \frac{\delta}{2}$.

We have already seen the value of the scale function of Bessel processes. Another useful concept is the *speed measure*

$$m_\delta(dx) := C_\delta (x^+)^{-2\frac{\delta-1}{\delta-2}} dx, \quad \delta < 2.$$

with $C_\delta > 0$. We define for $(B_t)_{t \geq 0}$ a BM with local times $(L_t^a)_{t,a}$

$$A_t := \int_0^t C_\delta ((B_s)^+)^{-2\frac{\delta-1}{\delta-2}} ds = \int L_t^a m_\delta(da)$$

$$\gamma_t := \inf\{u \geq 0 : A_u > t\}.$$

Theorem

Let ρ be a δ -Bessel process, $\delta > 0$. Then $(B_{\gamma_t})_{t \geq 0}$ and $(s(\rho_t))_{t \geq 0}$ have the same law. Moreover

$$\ell_t^a = L_{\gamma_t}^{a^{2-\delta}}.$$

See [Rogers-Williams, 2. vol., V.47-48]

Explicit computations

Let now $d \in \mathbb{N}$ and $B_t^{(d)} = (B_t^1, \dots, B_t^d)$ a d -dimensional Brownian motion started at $0 \in \mathbb{R}^d$. Then we have the following

Proposition

Let $a \in \mathbb{R}^d$. Then $(|a + B_t^{(d)}|)_{t \geq 0}$ has the same law as the d -Bessel process started at $x = |a|$.

Proof.

Since for all $a \in \mathbb{R}^d$, $\mathbb{P}(\exists t > 0 : a + B_t^{(d)} = 0)$ is 1 for $d = 1$ and 0 for $d \geq 2$, then by the Ito formula for $\rho_t := |a + B_t^{(d)}|$ for $d \geq 2$

$$\rho_t = |a| + \int_0^t \frac{d-1}{2} \frac{1}{\rho_s} ds + \int_0^t \frac{a + B_s^{(d)}}{|a + B_s^{(d)}|} \cdot dB_s^{(d)}.$$

The last term is a continuous martingale with quadratic variation equal to t , and by Lévy's Theorem it is a standard Brownian motion $(\hat{B}_t)_{t \geq 0}$.

Proposition

Let $\delta \geq 1$. The transition semigroup $(p_t^\delta(x, y))_{t \geq 0, x \geq 0, y \geq 0}$ of the δ -Bessel process is given for $t > 0$ and $y \geq 0$ by

$$p_t^\delta(x, y) = \frac{1}{t} \left(\frac{y}{x}\right)^\nu y \exp\left(-\frac{x^2 + y^2}{2t}\right) I_\nu\left(\frac{xy}{t}\right), \quad x > 0,$$

$$p_t^\delta(0, y) = \frac{1}{2^\nu t^{\nu+1} \Gamma(\nu + 1)} y^{2\nu+1} \exp\left(-\frac{y^2}{2t}\right),$$

where $\nu := \frac{\delta}{2} - 1$ and I_ν is the modified Bessel function of index ν

$$I_\nu(z) := \sum_{k=0}^{\infty} \frac{(z/2)^{2k+\nu}}{k! \Gamma(\nu + k + 1)}, \quad z \geq 0.$$

In particular $p_t(x, y) \sim Cy^{2\nu+1} = Cy^{\delta-1}$ as $y \downarrow 0$.

Two exercises

Let $f : \mathbb{R} \mapsto \mathbb{R}$ be a smooth function with bounded first derivative f' and consider the following SDE in \mathbb{R}

$$Z_t = x + \int_0^t f(Z_s) ds + B_t, \quad t \geq 0.$$

Let \mathbf{Q}_x be the law of $(Z_t)_{t \geq 0}$.

Exercise

Let $F : \mathbb{R} \mapsto \mathbb{R}$ such that $F' = f$. With the Girsanov theorem and the Ito formula show that

$$\mathbf{Q}_x|_{\mathcal{F}_t^0} = \exp \left(F(X_t) - F(x) - \frac{1}{2} \int_0^t (f'(X_s) + f^2(X_s)) ds \right) \cdot \mathbf{W}_x|_{\mathcal{F}_t^0}.$$

We recall that \mathbf{W}_x is the law of $(x + B_t)_{t \geq 0}$ and $(X_t)_{t \geq 0}$ is the canonical process.

Two exercises

We denote now by $(\mathbf{Q}_{x,y})_{y \in \mathbb{R}}$ a regular conditional distribution for $\mathbf{Q}_x[\cdot | X_1 = y]$, or in other words for the law of $(Z_t, t \in [0, 1])$ given Z_1 , i.e. for all Borel set $A \subset C([0, 1])$

$$\mathbf{Q}_{x,y}(A) = \mathbf{Q}_x[A | X_1 = y].$$

Let $\mathbf{W}_{x,y}$ be the law of the Brownian bridge from x to y over the interval $[0, 1]$, namely of $(x(1-t) + ty + B_t - tB_1)_{t \in [0,1]}$.

Exercise

We have for all $a, b \in \mathbb{R}$

$$\mathbf{Q}_{a,b} = \frac{1}{Z_{a,b}} \exp \left(-\frac{1}{2} \int_0^1 (f'(X_s) + f^2(X_s)) ds \right) \cdot \mathbf{W}_{a,b},$$

where $Z_{a,b} \in]0, +\infty[$ is a normalisation constant.

Back to Bessel processes

We want to consider for $c > 0$ and $\delta = 1 + 2c > 1$,

$$f(x) = \frac{c}{x} \mathbb{1}_{(x>0)} = \frac{\delta - 1}{2} \frac{1}{x} \mathbb{1}_{(x>0)},$$

which is of course not smooth and therefore requires some additional care. Let us note that the common term in the above exercises becomes

$$-\frac{1}{2} \int_0^1 (f'(X_s) + f^2(X_s)) ds = \frac{c - c^2}{2} \int_0^1 \frac{1}{X_s^2} ds.$$

Note that

$$\frac{c - c^2}{2} = -\frac{(\delta - 1)(\delta - 3)}{8} \begin{cases} < 0 & \text{for } \delta > 3 \\ = 0 & \text{for } \delta = 3 \\ > 0 & \text{for } \delta < 3. \end{cases}$$

Absolute continuity results

We define $T_0 := \inf\{t > 0 : X_t = 0\}$.

Proposition

Let $x > 0$ and $\delta \geq 2$. Then

$$\mathbf{P}_x^\delta|_{\mathcal{F}_t^0} = \left(\frac{X_{t \wedge T_0}}{x}\right)^{\frac{\delta-1}{2}} \exp\left(-\frac{(\delta-1)(\delta-3)}{8} \int_0^t \frac{1}{X_s^2} ds\right) \cdot \mathbf{W}_x|_{\mathcal{F}_t^0}.$$

Proof. If $f(x) = \frac{\delta-1}{2} \frac{1}{x} \mathbb{1}_{(x>0)}$, then since $X_{T_0} = 0$

$$\begin{aligned} & \exp\left(F(X_{t \wedge T_0}) - F(x) - \frac{1}{2} \int_0^{t \wedge T_0} (f'(X_s) + f^2(X_s)) ds\right) = \\ & = \left(\frac{X_{t \wedge T_0}}{x}\right)^{\frac{\delta-1}{2}} \exp\left(-\frac{(\delta-1)(\delta-3)}{8} \int_0^t \frac{1}{X_s^2} ds\right). \end{aligned}$$

See the lecture notes for the full proof. □

Bessel bridges

Let $x, y \geq 0$. For all Borel set $A \subset C([0, 1])$

$$\mathbf{P}_{x,y}^\delta(A) = \mathbf{P}_x^\delta[A \mid X_1 = y].$$

Let $\mathbf{W}_{x,y}$ the law of $(x(1-t) + ty + B_t - tB_1)_{t \in [0,1]}$, Brownian bridge from x to y over the interval $[0, 1]$.

Corollary

Let $a, b > 0$. Then

$$\mathbf{P}_{a,b}^3 = \frac{\mathbb{1}_{(T_0 > 1)}}{1 - \exp(-2ab)} \cdot \mathbf{W}_{a,b} = \mathbf{W}_{a,b}(\cdot \mid T_0 > 1). \quad (15)$$

For $\delta \geq 2$

$$\mathbf{P}_{a,b}^\delta = \frac{1}{Z_{a,b}^\delta} \exp\left(-\frac{(\delta-1)(\delta-3)}{8} \int_0^1 \frac{1}{X_s^2} ds\right) \cdot \mathbf{P}_{a,b}^3.$$

The Brownian excursion

Since $a, b \mapsto \mathbf{P}_{a,b}^\delta$ is continuous in the weak topology, we obtain

Corollary

$$\mathbf{P}_{0,0}^3 = \lim_{a \downarrow 0} \mathbf{W}_{a,a}(\cdot \mid T_0 > 1) = \lim_{a \downarrow 0} \mathbf{W}_{0,0}(\cdot \mid \inf X \geq -a). \quad (16)$$

$\mathbf{P}_{0,0}^3$ is called the law of the **normalised Brownian excursion**.

Note that

$$\mathbf{W}_{a,a}(T_0 > 1) = \mathbf{W}_{0,0}(\inf X \geq -a) = 1 - \exp(-2a^2),$$

$$\mathbf{W}_{0,0}(T_0 > 1) = \mathbf{W}_{0,0}(\inf X \geq 0) = 0,$$

so that the above conditioning is singular.

Chapter 4: The stochastic heat equation

Proposition

Let \mathcal{H} be a separable Hilbert space. There exists a process $(W(h), h \in \mathcal{H})$ such that $h \mapsto W(h)$ is linear, $W(h)$ is a centered real Gaussian random variable and

$$\mathbb{E}(W(h) W(k)) = \langle h, k \rangle_{\mathcal{H}}, \quad \forall h, k \in \mathcal{H}.$$

Proof.

Let $(Z_i)_i$ be a i.i.d. sequence of real standard Gaussian variables and $(h_i)_i$ a complete orthonormal system in \mathcal{H} and set

$$W(h) := \sum_{i=1}^{+\infty} \langle h, h_i \rangle_{\mathcal{H}} Z_i, \quad h \in \mathcal{H}.$$

This series converges in $L^2(\Omega)$.



Let now (T, \mathcal{B}, m) be a separable measurable space, with m a σ -finite measure. We apply the Proposition to $\mathcal{H} := L^2(T, \mathcal{B}, m)$, with canonical scalar product

$$\langle h, k \rangle_{\mathcal{H}} := \int_T h(x) k(x) m(dx), \quad h, k \in L^2(T, \mathcal{B}, m).$$

The process $(W(h), h \in \mathcal{H})$ is called a **white noise** over (T, \mathcal{B}, m) .

If $A \in \mathcal{B}$ and $m(A) < +\infty$, then $\mathbb{1}_A \in \mathcal{H}$ and we denote $W(A) := W(\mathbb{1}_A)$. If $A, B \in \mathcal{B}$ with $m(A) + m(B) < +\infty$ then

$$\mathbb{E}(W(A) W(B)) = m(A \cap B).$$

In particular, if $m(A \cap B) = 0$, then $\{W(A'), A' \subseteq A\}$ and $\{W(B'), B' \subseteq B\}$ are independent.

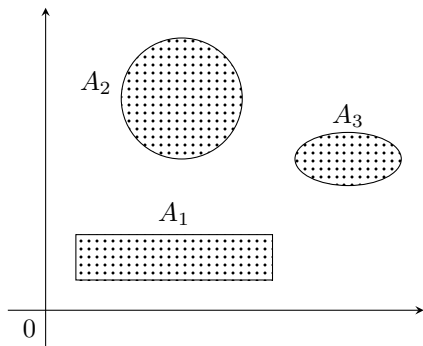


Figure : The family $(W(A_i))_i$ is Gaussian and independent since the sets A_i are pairwise disjoint. $W(A_i) \sim \mathcal{N}(0, m(A_i))$ and $W(\cup_i A_i) \sim \mathcal{N}(0, \sum_i m(A_i))$.

For all measurable set A , $W(A)$ is the amount of noise contained in A .

Finite dimensional white noise

Let us consider first the easiest case: $T = \{1, \dots, d\}$ and m is the counting measure.

In this case $L^2(T, \mathcal{B}, m) = \mathbb{R}^d$ and the white noise $W(h)$ can be realised as $W(h) = \langle W, h \rangle_{\mathbb{R}^d}$, where $W \sim \mathcal{N}(0, I)$.

Let now $T = \mathbb{R}$ endowed with the Borel σ -algebra and the Lebesgue measure λ_1 . Then for all $[a, b]$ and $[c, d]$ in \mathbb{R}

$$\mathbb{E}(W([a, b]) W([c, d])) = \lambda_1([a, b] \cap [c, d]).$$

Then the process

$$B_t := \begin{cases} W([0, t]), & t \geq 0, \\ W([t, 0]), & t < 0. \end{cases} \quad (17)$$

is (a modification of) a two-sided standard Brownian motion, and $W(dt)$ is simply called **white noise** over \mathbb{R} . In particular, the process $(W([0, t]), t \geq 0)$ is (a modification of) a standard BM.

Multi-dimensional Brownian motion

Let now $T = \mathbb{R} \times \{1, \dots, d\}$ endowed with the Borel σ -algebra and the measure $\lambda_1 \otimes m$ where λ_1 is the Lebesgue measure and m is the counting measure.

Then for all $[a, b]$ and $[c, d]$ in \mathbb{R} and for any $i, j \in \{1, \dots, d\}$

$$\mathbb{E}(W([a, b] \times \{i\}) W([c, d] \times \{j\})) = \lambda_1([a, b] \cap [c, d]) \mathbb{1}_{(i=j)}.$$

Then the process (B_t^1, \dots, B_t^d) , defined by

$$B_t^i := \begin{cases} W([0, t] \times \{i\}), & t \geq 0, \\ W([t, 0] \times \{i\}), & t < 0. \end{cases}$$

is (a modification of) a two-sided standard Brownian motion in \mathbb{R}^d .

Then a standard SDE with additive noise

$$dX_t = b(X_t) dt + dB_t$$

can be written, if $B_t = W([0, t])$, as

$$\dot{X}_t = b(X_t) + W = b(X_t) + \dot{B}_t.$$

This is just a notation and both formulae should be interpreted as

$$X_t = X_0 + \int_0^t b(X_s) ds + B_t, \quad t \geq 0.$$

Brownian sheet

If $T = \mathbb{R}_+^2 = [0, +\infty[^2$ endowed with the Borel σ -algebra and the Lebesgue measure λ_2 , then

$$\mathbb{E}(W([0, t] \times [0, t']) W([0, s] \times [0, s'])) = (t \wedge s) (t' \wedge s')$$

The process $(B(t, s) := W([0, t] \times [0, s]), t, s \geq 0)$ is called a **Brownian sheet** and $W(dt, ds)$ a **space-time white noise**. One can also use the notations

$$W(dt, ds) = \frac{\partial^2 B}{\partial t \partial s} = W(t, s).$$

Notice that the same construction can be done if $T = \mathbb{R}_+^d$: this gives a space-time white noise with a d -dimensional space variable.

Lemma

Let $(e_i)_i$ be a complete orthonormal system in $L^2([0, +\infty[)$. Then

1. Let $w_t^i := W(\mathbb{1}_{[0,t]} \otimes e_i)$, $t \geq 0$, $i \in \mathbb{N}$. Then $(w_t^i)_i$ is an iid sequence of standard Brownian motions.
2. For all $h \in L^2([0, +\infty[)$ and $t \geq 0$

$$W(\mathbb{1}_{[0,t]} \otimes h) = \sum_i w_t^i \langle e_i, h \rangle$$

where the equality is in $L^2(\Omega)$.

A **cylindrical Brownian motion** in a separable Hilbert space H is

$$\langle W_t, h \rangle := \sum_i B_t^i \langle e_i, h \rangle, \quad t \geq 0,$$

where $(e_i)_i$ is a complete orthonormal system in H and $(B^i)_i$ is an iid sequence of Brownian motions.

The stochastic heat equation

We want to study the stochastic PDE

$$\left\{ \begin{array}{l} \frac{\partial v}{\partial t} = \frac{1}{2} \frac{\partial^2 v}{\partial x^2} + W, \\ v(t, 0) = v(t, 1) = 0, \quad t \geq 0, \\ v(0, x) = v_0(x), \quad x \in [0, 1] \end{array} \right. \quad (18)$$

where $W(t, x)$ is a space-time white-noise over $[0, +\infty[\times [0, 1]$.

This is the first SPDE we encounter. It is interpreted in the PDE-weak sense: for all $h \in C_c^2(0, 1)$ and $t \geq 0$

$$\langle v_t, h \rangle = \langle v_0, h \rangle + \frac{1}{2} \int_0^t \langle v_s, h'' \rangle ds + \int_0^t \int_0^1 h(x) W(ds, dx).$$

The deterministic heat equation

Let us start from the heat equation without noise:

$$\begin{cases} \frac{\partial v}{\partial t} = \frac{1}{2} \frac{\partial^2 v}{\partial x^2}, \\ v(t, 0) = v(t, 1) = 0, & t > 0 \\ v(0, x) = v_0(x), & x \in [0, 1] \end{cases} \quad (19)$$

where $v_0 \in H := L^2(0, 1)$. We set for all $k \geq 1$:

$$e_k(x) := \sqrt{2} \sin(k\pi x), \quad x \in [0, 1]. \quad (20)$$

Note that $\{e_k\}_{k \geq 1}$ is a complete basis of eigenvectors of the second derivative with homogeneous Dirichlet boundary conditions:

$$\frac{d^2}{dx^2} e_k = -(\pi k)^2 e_k, \quad e_k(0) = e_k(1) = 0, \quad k \geq 1.$$

Fourier decomposition

We set

$$\lambda_k := \frac{(\pi k)^2}{2}, \quad k \geq 1,$$

The solution of the heat equation (19) is therefore

$$v(t, x) = \sum_{k \geq 1} e^{-t\lambda_k} \langle e_k, v_0 \rangle e_k(x), \quad t > 0, x \in [0, 1].$$

Since $|e_k(x)| \leq \sqrt{2}$ and $\sum_{k \geq 1} e^{-t\lambda_k} k^m < +\infty$ for all $m \in \mathbb{N}$, the above series converges uniformly on $[\varepsilon, +\infty[\times [0, 1]$ for all $\varepsilon > 0$, together with all its partial derivatives in t and x . One can write more compactly, using the semigroup notation,

$$v_t := v(t, \cdot) = e^{tA} v_0 := \sum_{k \geq 1} e^{-t\lambda_k} \langle e_k, v_0 \rangle e_k, \quad t \geq 0.$$

Fourier expansion of the SHE

Let us consider the scalar product of both terms of (18) and e_k . Setting $v_t^k := \langle v(t, \cdot), e_k \rangle$ we obtain

$$dv_t^k = -\frac{(k\pi)^2}{2} v_t^k dt + dB_t^k, \quad v_0^k = \langle v_0, e_k \rangle$$

$$B_t^k := \int_{[0,t] \times [0,1]} e_k(x) W(ds, dx) = W(\mathbb{1}_{[0,t]} \otimes e_k).$$

We proved in Lemma 26 that $(B_t^k, t \geq 0)_{k \geq 1}$ is an independent sequence of Brownian motions. Then $(v_t^k)_{k \geq 1}$ is an independent family of O-U processes of respective parameter $\lambda_k > 0$, with

$$v_t^k = e^{-\lambda_k t} v_0^k + \int_0^t e^{-\lambda_k(t-s)} dB_s^k, \quad t \geq 0.$$

An important remark is the following:

$$\sum_k \frac{1}{\lambda_k} = \sum_k \frac{2}{(\pi k)^2} < +\infty.$$

Fourier expansion of the SHE

Lemma

For all $t \geq 0$ and $v_0 \in H = L^2(0, 1)$ the series

$$V_t(v_0) := \sum_{k=1}^{+\infty} v_t^k e_k = e^{tA} v_0 + \sum_{k=1}^{+\infty} \left(\int_0^t e^{-\lambda_k(t-s)} dB_s^k \right) e_k \quad (21)$$

converges in $L^2(\Omega; H)$ to a well-defined r.v. with values in H .

Proof.

Since $v_t^k \sim \mathcal{N} \left(e^{-\lambda_k t} v_0^k, \frac{1}{2\lambda_k} (1 - e^{-2\lambda_k t}) \right)$, then

$$\mathbb{E} \left(\left\| \sum_{k=n+1}^m v_t^k e_k \right\|^2 \right) = \sum_{k=n+1}^m \left[e^{-2\lambda_k t} (v_0^k)^2 + \frac{1}{2\lambda_k} (1 - e^{-2\lambda_k t}) \right] \rightarrow 0$$

as $n, m \rightarrow +\infty$, since $\lambda_k = Ck^2$.



Path continuity

Until now we have considered V_t as a $L^2(0, 1)$ -valued random variable. However, if $x \in [0, 1]$ is fixed, then

$$v_n(t, x) := \sum_{k=1}^n v_t^k e_k(x) = \sum_{k=1}^n \langle v_t, e_k \rangle e_k(x) \in \mathbb{R}$$

is well defined and continuous. The deterministic part $e^{tA} v_0$ is simple to analyse, therefore let us suppose that $v_0 = 0$. Then since $e_k^2(\cdot) \leq 2$

$$\begin{aligned} \mathbb{E} (|v_n(t, x) - v_m(t, x)|^2) &= \sum_{k=n+1}^m \mathbb{E} \left((v_t^k)^2 \right) e_k^2(x) \\ &\leq 2 \sum_{k=n+1}^m \int_0^t e^{-2\lambda_k(t-s)} ds = 2 \sum_{k=n+1}^m \frac{1 - e^{-2\lambda_k t}}{2\lambda_k} \rightarrow 0 \end{aligned}$$

as $n, m \rightarrow +\infty$. Therefore, there exists a well defined stochastic process $(v(t, x), t \geq 0, x \in [0, 1])$, limit in $L^2(\mathbb{P})$ of $(v_n(t, x), t \geq 0, x \in [0, 1])$ as $n \rightarrow \infty$.

Lemma

Let $v_0 = 0$. For all $m \in \mathbb{N}$ there exists a constant $C_m < +\infty$ such that

$$\mathbb{E} \left(|v(t, x) - v(s, y)|^{2m} \right) \leq C_m \left(|t - s|^{\frac{m}{2}} + |x - y|^m \right),$$

for all $t, s \geq 0, x, y \in [0, 1]$.

Proof. Since $(v(t, x) - v(s, y))$ is a real Gaussian variable with 0 mean, in order to estimate its moments it is enough to compute the second one, i.e. it is enough to prove that for some constant C

$$\mathbb{E} \left(|v(t, x) - v(s, y)|^2 \right) \leq C \left(|t - s|^{\frac{1}{2}} + |x - y| \right).$$

First we have

$$|v_n(t, x) - v_n(s, y)|^2 \leq 2 |v_n(t, x) - v_n(s, x)|^2 + 2 |v_n(s, x) - v_n(s, y)|^2.$$

Now (recall that $v_0 = 0$)

$$\begin{aligned}
 \mathbb{E} (|v_n(s, x) - v_n(s, y)|^2) &= \\
 &= \mathbb{E} \left(\left| \sum_{k=1}^n v_s^k (e_k(x) - e_k(y)) \right|^2 \right) \\
 &= \sum_{k=1}^n \frac{1 - e^{-2\lambda_k s}}{2\lambda_k} (e_k(x) - e_k(y))^2 \leq \sum_{k=1}^n \frac{1 \wedge (|x - y| k)^2}{k^2} \\
 &\leq 1 \wedge |x - y| + \int_1^\infty \frac{1 \wedge (|x - y| k)^2}{k^2} dk \leq 3 |x - y|.
 \end{aligned}$$

With similar computations

$$\begin{aligned}
 \mathbb{E} (|v_n(t, x) - v_n(s, x)|^2) &= \\
 &= \sum_{k=1}^n e_k^2(x) \left[(1 - e^{-\lambda_k(t-s)})^2 \frac{1 - e^{-2\lambda_k s}}{2\lambda_k} + e^{-2\lambda_k s} \frac{1 - e^{-2\lambda_k(t-s)}}{2\lambda_k} \right] \\
 &\leq 2 \sum_{k=1}^n \frac{1 \wedge (|t-s|k^2)}{k^2} \leq 2 \left(1 \wedge |t-s| + \int_1^\infty \frac{1 \wedge (|t-s|k^2)}{k^2} dk \right) \\
 &\leq 6 \sqrt{|t-s|}.
 \end{aligned}$$

We have used the fact that

$$(1 - e^{-\lambda_k(t-s)})^2 \leq (1 \wedge [\lambda_k(t-s)])^2 \leq 1 \wedge [\lambda_k(t-s)].$$

The desired result follows if we let $n \rightarrow \infty$. □

Proposition

Let $v_0 = 0$. There exists a continuous modification of $(v(t, x), t \geq 0, x \in [0, 1])$, that we call v again. Moreover a.s. for all $\varepsilon \in]0, 1[$ and $T < +\infty$

$$\sup_{x, y \in [0, 1], t, s \in [0, T]} \frac{|v(t, x) - v(s, y)|}{|t - s|^{\frac{1-\varepsilon}{4}} + |x - y|^{\frac{1-\varepsilon}{2}}} < +\infty.$$

This proposition is a consequence of the Kolmogorov criterion stated for a inhomogeneous distance on \mathbb{R}^d .

The solution to the stochastic heat equation can be seen:

- ▶ as a continuous $L^2(0, 1)$ -valued process $(V_t)_{t \geq 0}$, solving the SDE

$$dV = AV dt + dW_t$$

where A is ∂_x^2 with homogeneous Dirichlet boundary condition and

$$W_t := \sum_i B_t^i e_i$$

is a cylindrical Brownian motion in $L^2(0, 1)$. This is the **Da Prato-Zabczyk** approach.

- ▶ as a bi-continuous real valued process $(v(t, x), t \geq 0, x \in [0, 1])$. This is the **Walsh** approach.

The invariant measure

A probability measure μ on H is said to be **invariant** for $(V_t)_{t \geq 0}$, see (27), if, given a r.v. \mathcal{Z} with law μ and independent of W , the process $(V_t(\mathcal{Z}))_{t \geq 0}$ is stationary.

An invariant probability measure μ of $(V_t)_{t \geq 0}$ is **reversible** if for all $T \geq 0$, the processes $(V_t(\mathcal{Z}))_{t \in [0, T]}$ and $(V_{T-t}(\mathcal{Z}))_{t \in [0, T]}$ have the same law.

Proposition

The law $\mathbf{W}_{0,0}$ of the brownian bridge $(B_x - xB_1, x \in [0, 1])$, with B a standard BM, is the unique invariant probability measure of $(V_t)_{t \geq 0}$. Moreover $\mathbf{W}_{0,0}$ is reversible for $(V_t)_{t \geq 0}$.

The proof of this proposition is split into several (simple) lemmas.

The invariant measure

First we have the *Karhunen-Loève* decomposition of the Brownian bridge.

Lemma

Let μ_{t,v_0} the law on $H = L^2(0, 1)$ of $V_t(v_0)$, solution to (18). Then $\mu_{t,v_0} \implies \mu$, law of the H -valued r.v.

$$\beta := \sum_{k=1}^{+\infty} \frac{1}{\pi k} Z_k e_k = \sum_{k=1}^{+\infty} \frac{1}{\sqrt{2\lambda_k}} Z_k e_k, \quad (22)$$

where $(Z_k)_{k \geq 1}$ is an i.i.d. sequence of $\mathcal{N}(0, 1)$ variables and $(e_k)_k$ is the complete orthonormal system of H defined in (20).

Proof.

Recall that $v_t^k \sim \mathcal{N}\left(e^{-\lambda_k t} v_0^k, \frac{1}{2\lambda_k}(1 - e^{-2\lambda_k t})\right)$. □

The invariant measure

Lemma

The $L^2(0, 1)$ -valued r.v. β has law $\mathbf{W}_{0,0}$.

Proof.

$$\mathbb{E}(\beta_x \beta_y) = \sum_{k=1}^{+\infty} \frac{1}{(\pi k)^2} e_k(x) e_k(y) =: \alpha(x, y), \quad x, y \in [0, 1].$$

$$\begin{cases} -\frac{\partial^2 \alpha}{\partial x^2} = \delta_y(\mathrm{d}x), \\ \alpha(0, y) = \alpha(1, y) = 0. \end{cases}$$

The unique solution to this equation is

$$\alpha(x, y) = x \wedge y - xy \quad x, y \in [0, 1]$$

which is the covariance function of a Brownian bridge on $[0, 1]$. □

What we have done so far

- ▶ We have seen that a **reflected dynamics** is associated with a **conditioning** of the invariant measure.
- ▶ The **stochastic heat equation** has the law of the **Brownian bridge** as invariant measure
- ▶ The Brownian bridge conditioned to be non-negative is the **3-Bessel bridge**, i.e. the normalised Brownian excursion.

Therefore we expect the **reflected stochastic heat equation** to have the law of **3-Bessel bridge** as invariant measure.

The next step is the **construction** of the solution u to this SPDE with reflection.

Then we shall see the impact that the **fine properties** of these Brownian processes have on u .

Since $W = \sum_k dB_t^k e_k$, we understand why the classical Ito calculus runs into trouble: if $\varphi \in C_c^2(\mathbb{R})$ then formally

$$\begin{aligned} d\varphi(v(t, x)) &= \left(\frac{1}{2} \frac{\partial^2 \varphi}{\partial x^2}(t, x) dt + \sum_k dB_t^k e_k(x) \right) \varphi'(v(t, x)) \\ &\quad + \frac{1}{2} \varphi''(v(t, x)) \sum_k \langle e_k, e_k \rangle dt \end{aligned}$$

and $\sum_k \langle e_k, e_k \rangle = +\infty$.

In fact the two terms in red

$$\begin{aligned} d\varphi(v(t, x)) = & \left(\frac{1}{2} \frac{\partial^2 v}{\partial x^2}(t, x) dt + \sum_k dB_t^k e_k(x) \right) \varphi'(v(t, x)) \\ & + \frac{1}{2} \varphi''(v(t, x)) \sum_k \langle e_k, e_k \rangle dt \end{aligned}$$

are ill-defined and compensate each other.

This is a **renormalisation** phenomenon.

Semilinear SPDEs

Let $f : \mathbb{R} \mapsto \mathbb{R}$ such that there exists a constant $L > 0$ with

$$|f(u) - f(v)| \leq L|u - v|, \quad \forall u, v \in \mathbb{R}.$$

We study the following SPDE in $(t, x) \in \mathbb{R}_+ \times [0, 1]$

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + f(u) + W \\ u(t, 0) = u(t, 1) = 0 \\ u(0, x) = u_0(x) \end{cases}$$

Interpreted in the PDE-weak sense

$$\begin{aligned} \langle u_t, h \rangle &= \langle u_0, h \rangle + \frac{1}{2} \int_0^t \langle u_s, h'' \rangle ds + \int_0^t \langle f(u_s), h \rangle ds \\ &+ \int_0^t \int_0^1 h(x) W(ds, dx) \end{aligned} \tag{23}$$

We set $U_t := u(t, \cdot)$, $U_t^k := \langle U_t, e_k \rangle$, $f_t^k := \langle f(U_t), e_k \rangle$,

$$B_t^k := \int_{[0,t] \times [0,1]} e_k(x) W(ds, dx) = W(\mathbb{1}_{[0,t]} \otimes e_k).$$

Then

$$dU_t^k = (-\lambda_k U_t^k + f_t^k) dt + dB_t^k, \quad U_0^k = \langle u_0, e_k \rangle$$

and, by applying the Ito formula to the process $t \mapsto e^{\lambda_k t} U_t^k$ we obtain

$$U_t^k = e^{-\lambda_k t} U_0^k + \int_0^t e^{-\lambda_k(t-s)} f_s^k ds + \int_0^t e^{-\lambda_k(t-s)} dB_s^k.$$

The $(B^k)_k$ are still iid BMs but the non-linearity f couples the U^k 's.

If we sum again over the Fourier basis

$$U_t = \sum_k \langle U_t^k, e_k \rangle e_k = e^{tA} u_0 + \int_0^t e^{(t-s)A} f(U_s) ds + W_A(t),$$

where the **stochastic convolution**

$$W_A(t) := \sum_{k=1}^{+\infty} \left(\int_0^t e^{-\lambda_k(t-s)} dB_s^k \right) e_k$$

is the solution of the SHE (18) with null initial condition, see (21).

If f is Lipschitz, then we can write a fixed point argument in $E_T := C([0, T]; H)$ with $\Gamma : E_T \mapsto E_T$ defined by $\Gamma(g) := h$, where

$$h_t := e^{tA} u_0 + \int_0^t e^{(t-s)A} f(g_s) ds + W_A(t), \quad t \in [0, T].$$

Higher space dimension

One can study the stochastic PDE for $t \geq 0, x \in \mathbb{R}^d$

$$\frac{\partial v}{\partial t} = \frac{1}{2} \Delta v + W,$$

where $W(t, x)$ is a space-time white-noise over $[0, +\infty[\times \mathbb{R}^d$.

The solution is well-defined as a Gaussian field, but has no continuous modification.

In fact, its solutions live in distribution spaces: the higher the dimension, the more irregular the solution.

Non-linear SPDEs become much more difficult and one needs the theory of Regularity Structures.

Reflection seems out of reach.

Chapter 5: Obstacle problems

Let $a \geq 0$. We fix a space-time white noise W on $[0, +\infty[\times [0, 1]$. We study the following SPDE with reflection:

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + f(u) + W + \eta \\ u(0, x) = u_0(x), \quad u(t, 0) = u(t, 1) = a \\ u \geq 0, \quad d\eta \geq 0, \quad \int u \, d\eta = 0 \end{array} \right. \quad (24)$$

where we assume that:

1. $u_0 : [0, 1] \mapsto \mathbb{R}$ is continuous and $u_0 \geq 0$.
2. $f : \mathbb{R} \mapsto \mathbb{R}$ is Lipschitz and bounded.

The Nualart-Pardoux equation

Definition

A pair (u, η) is said to be a solution of equation (24) if a.s.

1. $(u(t, x), t \geq 0, x \in [0, 1])$ is continuous
2. $u \geq 0, u(t, 0) = u(t, 1) = a$ for all $t \geq 0$ and $u(0, \cdot) = u_0$
3. $\eta(dt, dx)$ is a measure on $]0, +\infty[\times]0, 1[$ such that $\eta(]0, T] \times [\delta, 1 - \delta]) < +\infty$ for all $T, \delta > 0$
4. for all $t \geq 0$ and $h \in C_c^\infty(0, 1)$

$$\begin{aligned} \langle u_t, h \rangle &= \langle u_0, h \rangle + \frac{1}{2} \int_0^t \langle u_s, h'' \rangle ds + \int_0^t \langle f(u_s), h \rangle ds \\ &+ \int_0^t \int_0^1 h(x) W(ds, dx) + \int_0^t \int_0^1 h(x) \eta(ds, dx) \end{aligned} \quad (25)$$

5. $\int u d\eta = 0$ or, equivalently, the support of η is contained in $\{(t, x) : u(t, x) = 0\}$.

Reduction to a PDE with random obstacle

Let $a \geq 0$ and v be the unique solution to

$$\begin{cases} \frac{\partial v}{\partial t} = \frac{1}{2} \frac{\partial^2 v}{\partial x^2} + W, \\ v(t, 0) = v(t, 1) = a, \quad v(0, x) = u_0(x). \end{cases} \quad (26)$$

Then the function $z := u - v$ solves

$$\begin{cases} \frac{\partial z}{\partial t} = \frac{1}{2} \frac{\partial^2 z}{\partial x^2} + f(z + v) + \eta \\ z(0, x) = 0, \quad z(t, 0) = z(t, 1) = 0 \\ z \geq -v, \quad d\eta \geq 0, \quad \int (z + v) d\eta = 0. \end{cases} \quad (27)$$

The important remark here is that equation (27) is a PDE (rather than a SPDE) with **random obstacle** $-v$.

Theorem

Let $w \in C([0, T] \times [0, 1])$ with $w(0, \cdot) \geq 0$, $w(\cdot, 0) \geq 0$, $w(\cdot, 1) \geq 0$.
Then there exists a unique pair (z, η) such that

- ▶ $z \in C([0, T] \times [0, 1])$, $z(0, \cdot) = 0$, $z(\cdot, 0) = z(\cdot, 1) = 0$
- ▶ $\eta(dt, dx)$ is a measure on $]0, T[\times]0, 1[$ such that $\eta(]0, T[\times [\delta, 1 - \delta]) < +\infty$ for all $\delta > 0$
- ▶ For all $t \in [0, T]$ and $h \in C_c^\infty(0, 1)$

$$\begin{aligned} \langle z_t, h \rangle &= \frac{1}{2} \int_0^t \langle z_s, h'' \rangle ds + \int_0^t \langle f(z_s + w_s), h \rangle ds \\ &\quad + \int_0^t \int_0^1 h(x) \eta(ds, dx) \end{aligned} \tag{28}$$

- ▶ $z \geq -w$, $\int (z + w) d\eta = 0$.

Uniqueness

Let (z, η) and $(\bar{z}, \bar{\eta})$ two solutions. If $z - \bar{z}$ is regular enough

$$\begin{aligned} \frac{d}{dt} \|z - \bar{z}\|^2 &= \\ &= \langle z - \bar{z}, \partial_{xx}(z - \bar{z}) + 2(f(z) - f(\bar{z})) \rangle + 2 \int_0^1 (z - \bar{z})(d\eta - d\bar{\eta}) \\ &\leq -\|\partial_x(z - \bar{z})\|^2 + 2L\|z - \bar{z}\|^2 - 2 \int_0^1 (z d\bar{\eta} + \bar{z} d\eta) \\ &\leq 2L\|z - \bar{z}\|^2 \end{aligned}$$

where $\|\cdot\|$ is the norm in $L^2(0, 1)$. Since $\|z - \bar{z}\|^2$ is zero at $t = 0$, we conclude that $z \equiv \bar{z}$. This argument is not fully rigorous since $z - \bar{z}$ does not necessary enjoy the necessary regularity for the previous computations. However Nualart and Pardoux proved that this argument can be made rigorous. \square

Existence: penalisation

We introduce the following approximating problem:

$$\begin{cases} \frac{\partial z^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 z^\varepsilon}{\partial x^2} + f(z^\varepsilon + w) + \frac{(z^\varepsilon + w)^-}{\varepsilon} \\ z^\varepsilon(0, \cdot) = 0, \quad z^\varepsilon(t, 0) = z^\varepsilon(t, 1) = 0, \end{cases} \quad (29)$$

with $\varepsilon > 0$. We set

$$f_\varepsilon(r) := f(r) + \frac{(r^-)}{\varepsilon}, \quad r \in \mathbb{R}.$$

We suppose as usually that f is monotone non-increasing, so that

$$f_\varepsilon(r) - f_\varepsilon(r') \leq 0, \quad \forall r > r'.$$

Monotonicity

We show that $z^\varepsilon \leq z^{\varepsilon'}$ if $\varepsilon > \varepsilon'$. Since $f_\varepsilon(\cdot) \leq f_{\varepsilon'}(\cdot)$ and with an integration by parts:

$$\begin{aligned} \frac{d}{dt} \left\| (z^\varepsilon - z^{\varepsilon'})^+ \right\|^2 &= \\ &= 2 \left\langle (z^\varepsilon - z^{\varepsilon'})^+, \frac{1}{2} \partial_{xx} (z^\varepsilon - z^{\varepsilon'}) + f_\varepsilon(z^\varepsilon + w) - f_{\varepsilon'}(z^{\varepsilon'} + w) \right\rangle \\ &\leq - \left\| \partial_x (z^\varepsilon - z^{\varepsilon'})^+ \right\|^2 + 2 \left\langle (z^\varepsilon - z^{\varepsilon'})^+, f_{\varepsilon'}(z^\varepsilon + w) - f_{\varepsilon'}(z^{\varepsilon'} + w) \right\rangle \\ &\leq 0 \end{aligned}$$

where $\| \cdot \|$ is the norm in $L^2(0, 1)$.

Since $z_0^\varepsilon - z_0^{\varepsilon'} = 0$, we conclude that $z^\varepsilon \leq z^{\varepsilon'}$.

Three more steps, as for one-dimensional diffusions:

- ▶ The case of a smooth obstacle
- ▶ Continuity of the map $w \mapsto z^\varepsilon$ uniformly in $\varepsilon > 0$
- ▶ Conclusion.

The crucial point is the maximum principle of ∂_{xx}^2 , i.e. the fact that monotonicity is preserved.

Three more steps, as for one-dimensional diffusions:

- ▶ The case of a smooth obstacle
- ▶ Continuity of the map $w \mapsto z^\varepsilon$ uniformly in $\varepsilon > 0$
- ▶ Conclusion.

The crucial point is the maximum principle of ∂_{xx}^2 , i.e. the fact that monotonicity is preserved.

In our computations it was the simple formula:

$$\langle (z^\varepsilon - z^{\varepsilon'})^+, \partial_{xx}(z^\varepsilon - z^{\varepsilon'}) \rangle = - \left\| \partial_x(z^\varepsilon - z^{\varepsilon'})^+ \right\|^2 \leq 0.$$

Setting $w := v$ and $u^\varepsilon := z^\varepsilon + v$, where v is defined by (26) and z^ε by (29), then u^ε solves the SPDE

$$\left\{ \begin{array}{l} \frac{\partial u^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 u^\varepsilon}{\partial x^2} + f(u^\varepsilon) + \frac{(u^\varepsilon)^-}{\varepsilon} + W \\ u^\varepsilon(0, \cdot) = u_0, \quad u^\varepsilon(t, 0) = u^\varepsilon(t, 1) = a. \end{array} \right.$$

This is a particular example of (23).

It will be useful in order to compute the invariant measure of the reflected dynamics.

The invariant measure

We already expect the invariant measure of $(u_t)_{t \geq 0}$ to be $\mathbf{P}_{a,a}^3$, law of the 3-Bessel bridge $a \rightarrow a \geq 0$ (for $f = 0$).

Let us consider a Brownian motion $(B_t^{(d)})_{t \geq 0}$ in \mathbb{R}^d where $B^{(d)} = (B^1, \dots, B^d)$ and the B^i 's are iid standard BMs.

Let $V : \mathbb{R}^d \rightarrow \mathbb{R}$ be a smooth function and let

$$dX_t = \nabla V(X_t) dt + dB_t^{(d)}, \quad X_0 = x \in \mathbb{R}^d.$$

Then one can show that an invariant measure for $(X_t)_{t \geq 0}$ is given by

$$\exp(2V(x)) dx.$$

If this measure is finite on \mathbb{R}^d , we obtain an invariant probability measure.

Gradient systems

Let us consider again a semi-linear SPDE

$$\frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + f(u) + W.$$

Then $W = \sum_k \dot{B}^k e_k$ where $(e_k)_k$ is a c.o.s. in $H := L^2(0, 1)$ such that

$$\frac{d^2}{dx^2} e_k = -(\pi k)^2 e_k, \quad e_k(0) = e_k(1) = 0, \quad k \geq 1,$$

recall (20). Question: can we find $V : H \mapsto \mathbb{R}$ such that

$$du = \nabla V(u) dt + dW.$$

Here the gradient ∇ is in the Hilbert-structure of H :

$$\langle \nabla V(\zeta), h \rangle = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} (V(\zeta + \varepsilon h) - V(\zeta)).$$

Gradient systems

We set $A : D(A) \subset H = L^2(0, 1) \rightarrow H$

$$D(A) = \left\{ h \in H : \sum_{k \geq 1} \lambda_k^2 \langle e_k, h \rangle^2 < +\infty \right\},$$

$$Ah = - \sum_{k \geq 1} \lambda_k \langle e_k, h \rangle e_k, \quad h \in D(A),$$

recall that $\sum_k \lambda_k^{-1} < +\infty$. If $h \in C_c^2(0, 1)$ then

$$Ah = \frac{1}{2} \frac{d^2 h}{dx^2}.$$

Then we set for $\zeta \in D(A)$

$$V(\zeta) := \frac{1}{2} \langle A\zeta, \zeta \rangle + \langle F(\zeta), 1 \rangle$$

where $F : \mathbb{R} \rightarrow \mathbb{R}$, $F' = f$ and

$$\langle F(\zeta), 1 \rangle = \int_0^1 F(\zeta_x) dx.$$

Gradient systems

Then, if $\mathbb{R} \ni \varepsilon \rightarrow 0$ and $h \in D(A)$,

$$\frac{1}{\varepsilon} (\langle A(\zeta + \varepsilon h), \zeta + \varepsilon h \rangle - \langle A\zeta, \zeta \rangle) = 2\langle A\zeta, h \rangle + \varepsilon\langle Ah, h \rangle,$$

where we have used $\langle A\zeta, h \rangle = \langle \zeta, Ah \rangle$, and

$$\begin{aligned} \frac{1}{\varepsilon} \langle F(\zeta + \varepsilon h) - F(\zeta), 1 \rangle &= \int_0^1 \frac{1}{\varepsilon} (F(\zeta_x + \varepsilon h_x) - F(\zeta_x)) \, dx \\ &\rightarrow \int_0^1 F'(\zeta_x) h_x \, dx = \langle f(\zeta), h \rangle. \end{aligned}$$

Therefore

$$\begin{aligned} \langle \nabla V(\zeta), h \rangle &= \langle A\zeta + f(\zeta), h \rangle, \\ \nabla V(\zeta) &= A\zeta + f(\zeta). \end{aligned}$$

Gradient systems: finite-dimensional approximation

Let now $n \geq 1$. We note H_n the linear span of $\{e_1, \dots, e_n\}$ and $B_t^{(n)} := \sum_{k=1}^n B_t^k e_k$. Let $\Pi_n : H \mapsto H_n$ be the orthogonal projection

$$\Pi_n h := \sum_{k=1}^n \langle h, e_k \rangle e_k, \quad h \in H.$$

Then we set $A_n : H \mapsto H_n$ and $f^n : H \mapsto H_n$:

$$A_n := \Pi_n A \Pi_n = A \Pi_n = \Pi_n A, \quad f^n := \Pi_n \circ f \circ \Pi_n.$$

Let ζ^n be the solution to the SDE in H_n

$$\zeta_t^n = \zeta_t^n(z) = z + \int_0^t (A \zeta_s^n + f^n(\zeta_s^n)) \, ds + B_t^{(n)}, \quad z \in H_n.$$

Theorem

Fix $u_0 \in H$. Then a.s. $(\zeta_t^n(\Pi_n u_0))_{t \geq 0}$ converges to u in $C([0, T]; H)$.

Gradient systems: finite-dimensional approximation

We define the probability measure on H_n

$$\nu_n(d\zeta_n) := \frac{1}{Z_n} \exp(2V_n(\zeta_n)) d\zeta_n, \quad \zeta_n \in H_n,$$

where $d\zeta_n$ is the n -dimensional Lebesgue measure on the Hilbert space H_n and Z_n is a normalisation constant.

Then it is well known that ν_n is invariant and reversible for $(\zeta_t^n)_{t \geq 0}$, namely if \mathcal{Z}_n has law ν_n and is independent of W then $(\zeta_t^n(\mathcal{Z}_n))_{t \geq 0}$ is stationary and for all $T \geq 0$, the processes $(\zeta_t^n(\mathcal{Z}_n))_{t \in [0, T]}$ and $(\zeta_{T-t}^n(\mathcal{Z}_n))_{t \in [0, T]}$ have the same law.

Can we pass to the limit as $n \rightarrow +\infty$?

Since $2V(\zeta) = \langle A\zeta, \zeta \rangle + 2\langle F(\zeta), 1 \rangle$

$$\nu_n(d\zeta_n) := \frac{1}{\hat{Z}_n} \exp(2\langle F(\zeta_n), 1 \rangle) \mathcal{N}(0, Q_n)(d\zeta_n)$$

where $Q_n = \text{diag}\left(\frac{1}{2\lambda_1}, \dots, \frac{1}{2\lambda_n}\right)$.

Recall now (22). Then $\mathcal{N}(0, Q_n) \implies \mathbf{W}_{0,0}$, law of β . It is therefore simple to show that

$$\nu_n \implies \nu := \frac{1}{\hat{Z}} \exp(2\langle F(\zeta), 1 \rangle) \mathbf{W}_{0,0}(d\zeta).$$

By Skorokhod's representation theorem we can suppose that \mathcal{Z}_n converges a.s. to \mathcal{Z} in H .

A technical estimate

Under the usual one sided bound

$$f(r) - f(r') \leq L(r - r'), \quad \forall r > r',$$

we have the following estimate:

$$\|\zeta_t^n(z) - \zeta_t^n(\hat{z})\| \leq e^{Lt} \|z - \hat{z}\|.$$

This can be proved in the usual way, denoting $\zeta_t := \zeta_t^n(z)$ and $\hat{\zeta}_t := \zeta_t^n(\hat{z})$

$$\begin{aligned} \frac{d}{dt} \|\zeta_t - \hat{\zeta}_t\|^2 &= 2 \left\langle \zeta_t - \hat{\zeta}_t, A \left(\zeta_t - \hat{\zeta}_t \right) + f_\varepsilon(\zeta_t) - f_\varepsilon(\hat{\zeta}_t) \right\rangle \\ &\leq - \left\| \partial_x \left(\zeta_t - \hat{\zeta}_t \right) \right\|^2 + 2 \left\langle \zeta_t - \hat{\zeta}_t, f(\zeta_t) - f(\hat{\zeta}_t) \right\rangle \\ &\leq 2L \|\zeta_t - \hat{\zeta}_t\|^2. \end{aligned}$$

Therefore we have

- ▶ $(\zeta_t^n(\Pi_n u_0))_{t \geq 0}$ converges a.s. to $(u_t)_{t \geq 0}$ as $n \rightarrow +\infty$
- ▶ $z \mapsto \zeta_t^n(z)$ is Lipschitz, uniformly in n
- ▶ \mathcal{Z}_n converges a.s.
- ▶ $(\zeta_t^n(\mathcal{Z}_n))_{t \geq 0}$ is stationary

Then it is easy to see that $(\zeta_t^n(\mathcal{Z}_n))_{t \geq 0}$ converges a.s. to a stationary solution of the SPDE with reflection.

The penalised invariant measure

We consider now the penalised SPDE

$$\begin{cases} \frac{\partial u^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 u^\varepsilon}{\partial x^2} + f(u^\varepsilon) + \frac{(u^\varepsilon)^-}{\varepsilon} + W \\ u^\varepsilon(0, \cdot) = u_0, \quad u^\varepsilon(t, 0) = u^\varepsilon(t, 1) = a. \end{cases}$$

The invariant measure is

$$\nu_\varepsilon^a(d\zeta) := \frac{1}{Z_\varepsilon^a} \exp(2\langle F_\varepsilon(\zeta), 1 \rangle) \mathbf{W}_{a,a}(d\zeta),$$

where F_ε satisfies

$$F_\varepsilon(0) = 0, \quad F'_\varepsilon(y) := f(y) + \frac{y^-}{\varepsilon} = f_\varepsilon(y).$$

The penalised invariant measure

Note that

$$\frac{d}{dr} (r^-)^2 = -2r^-.$$

Then for $a > 0$

$$\nu_\varepsilon^a(d\zeta) = \frac{1}{Z_\varepsilon^a} \exp\left(2\langle F(\zeta), 1 \rangle - \frac{1}{\varepsilon} \langle (\zeta^-)^2, 1 \rangle\right) \mathbf{W}_{a,a}(d\zeta),$$

converges as $\varepsilon \downarrow 0$ to

$$\nu^a(d\zeta) := \frac{1}{Z^a} \exp(2\langle F(\zeta), 1 \rangle) \mathbb{1}_K(\zeta) \mathbf{W}_{a,a}(d\zeta),$$

where $K := \{u_0 : [0, 1] \rightarrow \mathbb{R} : u_0 \in L^2(0, 1), u_0 \geq 0\}$.

We have seen in (15) that

$$\mathbf{P}_{a,a}^3 = \mathbf{W}_{a,a}(\cdot | T_0 > 1) = \mathbf{W}_{a,a}(\cdot | K).$$

Then

$$\nu^a(d\zeta) := \frac{1}{\hat{Z}^a} \exp(2\langle F(\zeta), 1 \rangle) \mathbf{P}_{a,a}^3(d\zeta),$$

and as $a \downarrow 0$

$$\nu^a(d\zeta) \implies \nu^0(d\zeta) := \frac{1}{\hat{Z}^0} \exp(2\langle F(\zeta), 1 \rangle) \mathbf{P}_{0,0}^3(d\zeta).$$

In particular if $f \equiv 0$ then the invariant measure of the SPDE with reflection is simply $\mathbf{P}_{a,a}^3$.

The situation

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- ▶ We have constructed the solution (u, η) to the SPDE with reflection (24)
- ▶ We have computed the (unique) probability invariant measure

$$\nu^a(d\zeta) := \frac{1}{\hat{Z}^a} \exp(2\langle F(\zeta), 1 \rangle) \mathbf{P}_{a,a}^3(d\zeta),$$

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for $a \geq 0$.

Comments:

- ▶ Walsh and Da Prato-Zabczyk reconciled
- ▶ In the slides we only prove results on **stationary** u , in the lecture notes the general case is treated
- ▶ u is the weak limit of discrete interfaces: ask **Cyril Labbé** for a confirmation.

Chapter 6: Integration by parts formulae

Let $(\rho_t, \ell_t)_{t \geq 0}$ be the solution to the SDE with reflection (4)

$$\rho_t = x + B_t + \int_0^t f(\rho_s) ds + \ell_t.$$

Then we proved in (6) that

$$\int_{\mathbb{R}_+} e^{2F(x)} \mathbb{E}(\ell_t(x)) dx = \frac{t}{2} e^{2F(0)}, \quad t \geq 0.$$

where $F' = f$.

This formula allowed us to prove that for $\delta > 1$ the equation

$$\rho_t = x + B_t + \frac{\delta - 1}{2} \int_0^t \rho_s^{-1} ds + \ell_t$$

has reflection term $\ell \equiv 0$ and the solution is a δ -Bessel process.

The Revuz measure of η

For reasons which will be clear later, it would be very useful to have a similar formula for (u, η) .

In this case, such the analogous result would be an explicit formula for

$$\int \nu^a(\mathrm{d}u_0) \mathbb{E} \left[\int_0^t \int_0^1 h(x) \varphi(u_s) \eta(\mathrm{d}s, \mathrm{d}x) \right]$$

where $h : [0, 1] \rightarrow \mathbb{R}$ and $\varphi : H \rightarrow \mathbb{R}$ are bounded Borel.

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$$\int \nu^a(du_0) \mathbb{E} \left[\int_0^t \int_0^1 h(x) \varphi(u_s) \eta(ds, dx) \right]$$

where $h : [0, 1] \rightarrow \mathbb{R}$ and $\varphi : H \rightarrow \mathbb{R}$ are bounded Borel.

The one-dimensional formula was simpler since there was no spatial variable x , no $h(x)$ and no φ , since

$$\int_0^t \varphi(\rho_s) dl_s = \varphi(0) l_t,$$
$$\int_{\mathbb{R}_+} e^{2F(x)} \mathbb{E} \left[\int_0^t \varphi(\rho_s(x)) dl_s(x) \right] dx = \frac{t}{2} \varphi(0) e^{2F(0)}.$$

Integration by parts

Penalisation:

$$\rho_t^n = x + B_t + n \int_0^t (\rho_s^n)^- ds + \int_0^t f(\rho_s^n) ds, \quad t \geq 0.$$

One can prove that

$$\begin{aligned} & \lim_{\varepsilon \downarrow 0} \int \mu_n(dx) \mathbb{E} \left[\int_0^t \varphi(\rho_s^n) n (\rho_s^n)^- ds \right], \\ &= \int \mu(dx) \mathbb{E} \left[\int_0^t \varphi(\rho_s) dl_s \right]. \end{aligned}$$

By stationarity

$$\int \mu_n(dx) \mathbb{E} \left[\int_0^t \varphi(\rho_s^n) n (\rho_s^n)^- ds \right] = t \int \mu_n(dx) \varphi(x) n x^-.$$

We can prove with a change of variable as in (9) that

$$\lim_{n \rightarrow +\infty} \int \mu_n(dx) \varphi(x) n x^- = \frac{1}{2} \varphi(0) e^{2F(0)}.$$

Integration by parts

The difficulty comes from

$$\mu_n(dx) n x^- = e^{-n(x^-)^2 + 2F(x)} n x^- dx.$$

However we can write

$$e^{-n(x^-)^2} n x^- = \frac{1}{2} \frac{d}{dx} e^{-n(x^-)^2}.$$

Integration by parts

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$$\mu_n(dx) n x^- = e^{-n(x^-)^2 + 2F(x)} n x^- dx.$$

However we can write

$$e^{-n(x^-)^2} n x^- = \frac{1}{2} \frac{d}{dx} e^{-n(x^-)^2}.$$

Therefore, if $\varphi \in C_c^1(\mathbb{R})$, we can integrate by parts and obtain

$$\begin{aligned} \int \mu_n(dx) \varphi(x) n x^- &= \int e^{2F(x)} \varphi(x) \frac{1}{2} \frac{d}{dx} e^{-n(x^-)^2} dx \\ &= -\frac{1}{2} \int \frac{d}{dx} (\varphi e^{2F}) e^{-n(x^-)^2} dx \rightarrow -\frac{1}{2} \int_{\mathbb{R}_+} \frac{d}{dx} (\varphi e^{2F}) dx. \end{aligned}$$

If we integrate by parts again, we find now

$$\lim_{n \rightarrow +\infty} \int \mu_n(dx) \varphi(x) n x^- = \frac{1}{2} \varphi(0) e^{2F(0)}, \quad \forall \varphi \in C_c^1(\mathbb{R}).$$

Can we repeat the same trick for (u, η) ?

This means integrating by parts w.r.t. to

$$\mathbf{P}_{a,a}^3 = \mathbf{W}_{a,a}(\cdot | T_0 > 1) = \mathbf{W}_{a,a}(\cdot | K)$$

where $K = \{u_0 : [0, 1] \rightarrow \mathbb{R} : u_0 \in L^2(0, 1), u_0 \geq 0\}$.

Integration by parts

Consider a regular bounded open set $O \subset \mathbb{R}^d$. Then the classical Gauss-Green formula states that for all $h \in \mathbb{R}^d$

$$\int_O (\partial_h \varphi) \rho \, dx = - \int_O \varphi \frac{\partial_h \rho}{\rho} \rho \, dx - \int_{\partial O} \varphi \langle \hat{n}, h \rangle \rho \, d\sigma$$

- ▶ $\varphi, \rho \in C_b^1(O)$ with $\lambda \leq \rho \leq \lambda^{-1}$, $\lambda \in]0, 1]$ is a constant,
- ▶ \hat{n} is the inward-pointing normal vector to the boundary ∂O
- ▶ σ is the surface measure on ∂O
- ▶ $\partial_h \varphi$ is the directional derivative of φ along h
- ▶ $\partial_h \log \rho = (\partial_h \rho) / \rho$.

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- ▶ $\partial_h \varphi$ is the directional derivative of φ along h
- ▶ $\partial_h \log \rho = (\partial_h \rho) / \rho$.

For us, $\mathbf{W}_{a,a} = \rho \, dx$, $K = O$.

What is the analog of $\rho \, d\sigma$? and of \hat{n} ? and of ∂O ?

An example

Let $\mu = \mathcal{N}(0, \frac{1}{2\lambda})$. Then

$$\int \varphi' d\mu = \int 2\lambda x \varphi(x) \mu(dx)$$

$$\int_{\mathbb{R}_+} \varphi' d\mu = \int_{\mathbb{R}_+} \lambda x \varphi(x) \mu(dx) - \sqrt{\frac{\lambda}{\pi}} \varphi(0).$$

Here $\mu(dx) = \rho(x) dx = \sqrt{\frac{\lambda}{\pi}} \exp(-\lambda x^2) dx$,

$$\frac{\partial \rho}{\rho}(x) = -2\lambda x.$$

Integration by parts on the Gaussian measure

$$\int_H \partial_h \varphi \, d\mathbf{W}_{0,0} = - \int_H \langle \zeta, h'' \rangle \varphi(\zeta) \, \mathbf{W}_{0,0}(d\zeta)$$

- ▶ $\langle \cdot, \cdot \rangle$ is the scalar product in $H := L^2(0, 1)$
- ▶ $\varphi : H \mapsto \mathbb{R}$ is bounded and smooth
- ▶ $h \in C_c^2(0, 1)$, h'' is the second derivative of h
- ▶ $\partial_h \varphi$ is the directional derivative of φ along h :

$$\partial_h \varphi(\zeta) = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} (\varphi(\zeta + \varepsilon h) - \varphi(\zeta)).$$

The boundary measure

$$\begin{aligned} \mathbf{P}_{a,a}^3 [\partial_h \varphi] &= -\mathbf{P}_{a,a}^3 [\varphi(X) \langle X, h'' \rangle] \\ &\quad - \int_0^1 dr h(r) \gamma(r, a) \mathbf{P}_{a,a}^3 [\varphi(X) | X_r = 0]. \end{aligned}$$

where $\gamma(r, a) \geq 0$ is an explicit function of $r \in]0, 1[$, $a \geq 0$.

$$\int_{\mathcal{O}} (\partial_h \varphi) \rho \, dx = - \int_{\mathcal{O}} \varphi \frac{\partial_h \rho}{\rho} \rho \, dx - \int_{\partial \mathcal{O}} \varphi \langle \hat{n}, h \rangle \rho \, d\sigma$$

The boundary measure

By the Markov property and the Brownian scaling of $\mathbf{P}_{a,a}^3$

$$\mathbf{P}_{a,b}^\delta [\varphi(X) | X_r = c] = \int \varphi(T_r(k_1, k_2)) \mathbf{P}_{a,c}^\delta(dk_1) \mathbf{P}_{c,b}^\delta(dk_2)$$

where for all $r \in]0, 1[$ we have the scaling-plus-concatenation map $T_r : L^2(0, 1) \times L^2(0, 1) \mapsto L^2(0, 1)$,

$$\begin{aligned} [T_r(k_1, k_2)](\tau) &:= \\ &:= \sqrt{r} k_1 \left(\frac{\tau}{r} \right) \mathbb{1}_{(\tau \leq r)} + \sqrt{1-r} k_2 \left(\frac{\tau-r}{1-r} \right) \mathbb{1}_{(r < \tau \leq 1)}. \end{aligned}$$

The boundary measure

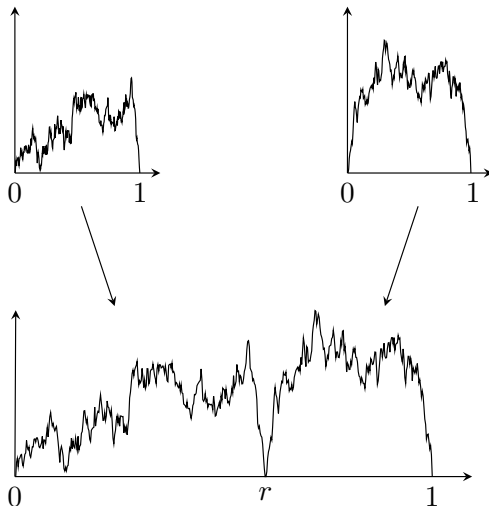


Figure : A typical path under the boundary measure and the action of T_r .

A random walk model

Let $(Y_i)_{i \in \mathbb{N}}$ be i.i.d. with $Y_i \sim \mathcal{N}(0, 1)$. For $n \in \mathbb{N}$ and $y \in \mathbb{R}$ we set

$$S_n := Y_1 + \cdots + Y_n, \quad g_t(y) = \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{y^2}{2t}\right).$$

P_N is the law of (S_1, \dots, S_N) under the conditioning $\{S_{N+1} = 0\}$. For all Borel set $A \subseteq \mathbb{R}^N$ with $\phi_0 := \phi_{N+1} := 0$

$$\begin{aligned} P_N(A) &= \lim_{\varepsilon \downarrow 0} \frac{\mathbb{E} [\mathbb{1}_A(S_1, \dots, S_N) \mathbb{1}_{[0, \varepsilon]}(S_{N+1})]}{\mathbb{P}(S_{N+1} \in [0, \varepsilon])} \\ &= \frac{1}{C_N} \int_{\mathbb{R}^N} \mathbb{1}_A(\phi) \exp\{-H_N(\phi)\} d\phi \end{aligned}$$

where

$$H_N(\phi) := \frac{1}{2} \sum_{i=1}^{N+1} (\phi_i - \phi_{i-1})^2.$$

A conditioned random walk

We set for $N \geq 1$, $\Omega_N^+ := \mathbb{R}_+^N = [0, \infty[^N$ and

$$dP_N^+ = \frac{1}{Z_N} \exp\{-H_N(\phi)\} \mathbb{1}_{(\phi \in \Omega_N^+)} d\phi$$

where Z_N is a normalisation constant. In particular

$$P_N^+ = P_N(\cdot | \Omega_N^+).$$

We define the Brownian scaling

$$\mathbb{R}^N \ni \phi \mapsto \Lambda_N(\phi)(x) := \frac{1}{\sqrt{N}} \phi_{[Nx]}, \quad x \in [0, 1],$$

$$\mathbf{P}_N := \Lambda_N^*(P_N), \quad \mathbf{P}_N^+ := \Lambda_N^*(P_N^+).$$

Proposition

As $N \rightarrow +\infty$, \mathbf{P}_N converges weakly to $\mathbf{W}_{0,0}$ and \mathbf{P}_N^+ to $\mathbf{P}_{0,0}^3$.

Integration by parts in finite dimension

Lemma

For all $F \in C_b^1(\mathbb{R}^N)$ and $c \in \mathbb{R}^N$ with $c_0 := c_{N+1} := 0$

$$\int_{\mathbb{R}^N} \sum_{i=1}^N c_i \frac{\partial F}{\partial \phi_i} dP_N = - \int_{\mathbb{R}^N} \sum_{i=1}^N c_i (\phi_{i+1} + \phi_{i-1} - 2\phi_i) F(\phi) P_N(d\phi)$$

and passing to the limit $N \rightarrow +\infty$ under Brownian scaling

$$\int_H \partial_h \varphi d\mathbf{W}_{0,0} = - \int_H \langle \zeta, h'' \rangle \varphi(\zeta) \mathbf{W}_{0,0}(d\zeta)$$

for all $h \in C_c^2(0, 1)$ and $\varphi \in C_b^1(H)$.

Integration by parts in finite dimension

Lemma

For all $F \in C_b^1(\mathbb{R}^N)$ and $c \in \mathbb{R}^N$ with $c_0 := c_{N+1} := 0$

$$\begin{aligned} & \int_{\mathbb{R}_+^N} \sum_{i=1}^N c_i \frac{\partial F}{\partial \phi_i} dP_N^+ = \\ & = - \int_{\mathbb{R}_+^N} \sum_{i=1}^N c_i (\phi_{i+1} + \phi_{i-1} - 2\phi_i) F(\phi) P_N^+(d\phi) \\ & \quad - \sum_{i=1}^N c_i \frac{Z_{i-1} Z_{N-i}}{Z_N} \int_{\mathbb{R}_+^{i-1} \times \mathbb{R}_+^{N-i}} F(\alpha \oplus \beta) P_{i-1}^+(d\alpha) P_{N-i}^+(d\beta) \end{aligned}$$

where $\alpha \oplus \beta := (\alpha_1, \dots, \alpha_{i-1}, 0, \beta_1, \dots, \beta_{N-i})$.

The point is that the boundary of \mathbb{R}_+^N is

$$\partial(\mathbb{R}_+^N) = \bigcup_{i=1}^N \mathbb{R}_+^{i-1} \times \{0\} \times \mathbb{R}_+^{N-i}.$$

For all $i \in \{1, \dots, N\}$ we can apply a one-dimensional IbPF fixing ϕ_j for $j \neq i$

$$\int_{\mathbb{R}_+} \frac{\partial F}{\partial \phi_i} d\phi_i = - \int_{\mathbb{R}_+} (\phi_{i+1} + \phi_{i-1} - 2\phi_i) F(\phi) d\phi_i - \frac{1}{Z_N} F(\psi^i) \exp\{-H_N(\psi^i)\}$$

where $\psi^i = (\phi_1, \dots, \phi_{i-1}, 0, \phi_{i+1}, \dots, \phi_N)$.

Now

$$\begin{aligned} H_N(\phi_1, \dots, \phi_{i-1}, \mathbf{0}, \phi_{i+1}, \dots, \phi_N) &= \\ &= H_{i-1}(\phi_1, \dots, \phi_{i-1}) + H_{N-i}(\phi_{i+1}, \dots, \phi_N). \end{aligned}$$

and therefore

$$\begin{aligned} \frac{1}{Z_N} \int_{\mathbb{R}_+^{\{1, \dots, N\} \setminus \{i\}}} F(\psi^i) \exp \{-H_N(\psi^i)\} \, d\psi &= \\ &= \frac{1}{Z_N} \int_{\mathbb{R}_+^i \times \mathbb{R}_+^{N-i}} F(\alpha \oplus \beta) \exp \{-H_N(\alpha \oplus \beta)\} \, d\alpha \, d\beta \\ &= \frac{Z_{i-1} Z_{N-i}}{Z_N} \int_{\Omega_{i-1}^+ \times \Omega_{N-i}^+} F(\alpha \oplus \beta) P_{i-1}^+(d\alpha) P_{N-i}^+(d\beta). \end{aligned}$$

This concludes the proof. □

$N \rightarrow +\infty$

$$\begin{aligned} & \int_{\mathbb{R}_+^N} \sum_{i=1}^N c_i \frac{\partial F}{\partial \phi_i} dP_N^+ = \\ & = - \int_{\mathbb{R}_+^N} \sum_{i=1}^N c_i (\phi_{i+1} + \phi_{i-1} - 2\phi_i) F(\phi) P_N^+(d\phi) \\ & - \sum_{i=1}^N c_i \frac{Z_{i-1} Z_{N-i}}{Z_N} \int_{\mathbb{R}_+^{i-1} \times \mathbb{R}_+^{N-i}} F(\alpha \oplus \beta) P_{i-1}^+(d\alpha) P_{N-i}^+(d\beta) \end{aligned}$$

Under Brownian rescaling as $N \rightarrow +\infty$:

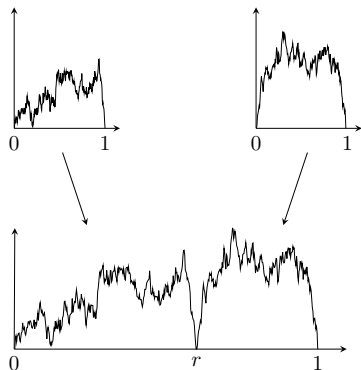
$$\begin{aligned} \mathbf{P}_{0,0}^3 [\partial_h \varphi] &= -\mathbf{P}_{0,0}^3 [\varphi(X) \langle X, h'' \rangle] \\ & - \int_0^1 dr h(r) \gamma(r, 0) \mathbf{P}_{0,0}^3 \otimes \mathbf{P}_{0,0}^3 [\varphi(T_r)]. \end{aligned}$$

The boundary measure

where for all $r \in]0, 1[$, $T_r : L^2(0, 1) \times L^2(0, 1) \mapsto L^2(0, 1)$,

$$[T_r(k_1, k_2)](\tau) :=$$

$$:= \sqrt{r} k_1 \left(\frac{\tau}{r} \right) \mathbb{1}_{(\tau \leq r)} + \sqrt{1-r} k_2 \left(\frac{\tau-r}{1-r} \right) \mathbb{1}_{(r < \tau \leq 1)}.$$



Theorem

For all bounded Borel $\varphi : H \mapsto \mathbb{R}$ and $h \in C_c(0, 1)$

$$\begin{aligned} \int \nu^a(\mathrm{d}u_0) \mathbb{E} \left[\int_0^t \int_0^1 h(x) \varphi(u_s) \eta(\mathrm{d}s, \mathrm{d}x) \right] &= \\ &= \frac{t}{2Z^a} \int_0^1 \mathrm{d}r h(r) \gamma(r, a) \int \varphi(\zeta) e^{2F(\zeta)} \Sigma_a(r, \mathrm{d}\zeta). \end{aligned}$$

where $\Sigma_a(r, \cdot) := \mathbf{P}_{a,a}^3[\cdot | X_r = 0]$.

We set

$$\eta(ds, h) := \int_0^1 h(x) \eta(ds, dx),$$

$$\eta^\varepsilon(ds, h) := \int_0^1 h(x) \frac{1}{\varepsilon} (u^\varepsilon(s, x))^- dx ds = \frac{1}{\varepsilon} \langle h, (u_s^\varepsilon)^- \rangle ds,$$

We need to prove two formulae:

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \int \nu_\varepsilon^a(du_0) \mathbb{E} \left[\int_0^t \varphi(u_s^\varepsilon) \eta^\varepsilon(ds, h) \right] &= \\ &= \int \nu^a(du_0) \mathbb{E} \left[\int_0^t \varphi(u_s) \eta(ds, h) \right], \\ \lim_{\varepsilon \downarrow 0} \int \nu_\varepsilon^a(du_0) \mathbb{E} \left[\int_0^t \varphi(u_s^\varepsilon) \eta^\varepsilon(ds, h) \right] &= \\ &= \frac{1}{2Z^a} \int_0^1 dr h(r) \gamma(r, a) \int \varphi(\zeta) e^{2F(\zeta)} \Sigma_a(r, d\zeta). \end{aligned}$$

Let $\varphi \in C_b^1(H)$. By an IbPF

$$\begin{aligned}
 & \int \nu_\varepsilon^a(d\zeta) \varphi(\zeta) \langle h, \frac{1}{\varepsilon} \zeta^- \rangle = \\
 &= \frac{1}{Z_\varepsilon^a} \int \mathbf{W}_{a,a}(d\zeta) \varphi(\zeta) \langle h, \frac{1}{\varepsilon} \zeta^- \rangle \exp \left(\langle 2F(\zeta) - \frac{1}{\varepsilon} (\zeta^-)^2, 1 \rangle \right) \\
 &= \frac{1}{Z_\varepsilon^a} \int \mathbf{W}_{a,a}(d\zeta) \varphi(\zeta) \exp(2\langle F(\zeta), 1 \rangle) \left\langle h, \frac{1}{2} \nabla \exp \left(-\frac{1}{\varepsilon} \langle (\zeta^-)^2, 1 \rangle \right) \right\rangle \\
 &= -\frac{1}{Z_\varepsilon^a} \int \mathbf{W}_{a,a}(d\zeta) \left(\langle \nabla \varphi(\zeta), h \rangle + \varphi(\zeta) \left(\frac{1}{2} \langle h'', \zeta \rangle + \langle f(\zeta), h \rangle \right) \right) \\
 &\quad \cdot \exp \left(\langle 2F(\zeta) - \frac{1}{\varepsilon} (\zeta^-)^2, 1 \rangle \right) \\
 &= - \int \nu_\varepsilon^a(d\zeta) \left(\langle \nabla \varphi(\zeta), h \rangle + \varphi(\zeta) \left(\frac{1}{2} \langle h'', \zeta \rangle + \langle f(\zeta), h \rangle \right) \right)
 \end{aligned}$$

Then, letting $\varepsilon \downarrow 0$

$$\begin{aligned}
 & \int \nu_\varepsilon^a(d\zeta) \varphi(\zeta) \langle h, \frac{1}{\varepsilon} \zeta^- \rangle \rightarrow \\
 & \rightarrow - \int \nu^a(d\zeta) \left(\langle \nabla \varphi(\zeta), h \rangle + \varphi(\zeta) \left(\frac{1}{2} \langle h'', \zeta \rangle + \langle f(\zeta), h \rangle \right) \right) \\
 & = \frac{1}{2Z^a} \int_0^1 dr h(r) \gamma(r, a) \int \varphi(\zeta) e^{2F(\zeta)} \Sigma_a(r, d\zeta)
 \end{aligned}$$

where we have integrated by parts again in the last equality. \square

The contact set

We denote by $\pi : [0, +\infty[\times [0, 1] \mapsto [0, +\infty[$ the projection $(t, x) \mapsto t$, and for a set $S \subset [0, +\infty[\times [0, 1]$ we write

$$S_t := \{x \in [0, 1] : (t, x) \in S\}, \quad t \geq 0.$$

Theorem

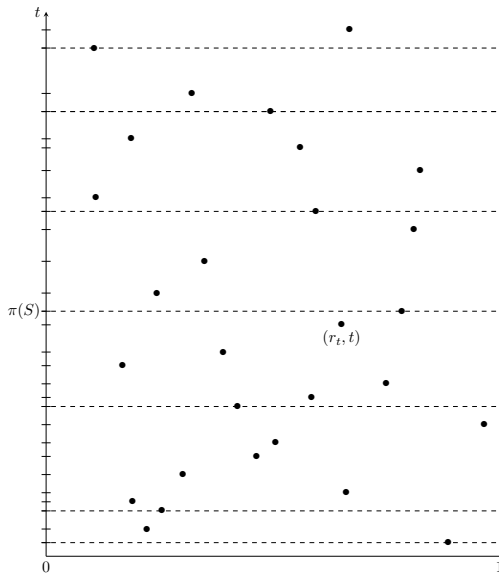
Let (u, η) be the stationary solution to equation (24). Let us denote by

$$\mathcal{C} := \{(t, x) : u(t, x) = 0, t > 0, x \in]0, 1[\}$$

the contact set and let us recall that the support of η is contained in \mathcal{C} . Then a.s. the set $\pi(\mathcal{C})$ has zero Lebesgue measure and there exists a measurable set $S \subset \mathcal{C}$ such that

1. $\eta(\mathcal{C} \setminus S) = 0$
2. for all $t > 0$, either $S_t = \emptyset$ or $S_t = \{r_t\}$, with $r_t \in]0, 1[$.
3. if $S_t = \{r_t\}$, then $u(t, x) > 0$ for all $x \in]0, 1[\setminus \{r_t\}$ and $u(t, r_t) = 0$.

The contact set



Let $I_1, I_2 \subset]0, 1[$ be closed intervals with $I_1 \cap I_2 = \emptyset$. Let $\varphi : C([0, 1]) \rightarrow \mathbb{R}$ be defined by

$$\varphi(\zeta) := \mathbb{1}_{(\inf_{I_1} \zeta = \inf_{I_2} \zeta = 0)}, \quad \zeta \in C([0, 1]).$$

Then for all $h \geq 0$

$$\begin{aligned} & \int \nu^a(du_0) \mathbb{E} \left[\int_0^t \int_0^1 h(x) \varphi(u_s) \eta(ds, dx) \right] = \\ &= \frac{t}{2Z^a} \int_0^1 dr h(r) \gamma(r, a) \int \varphi(\zeta) e^{2F(\zeta)} \Sigma_a(r, d\zeta) \\ &= 0. \end{aligned}$$

If we consider $I_1 = [q_1, q_2], I_2 = [q_3, q_4]$ with $q_i \in \mathbb{Q}$ then a.s. for $\eta(ds \times [0, 1])$ -a.s. $s, u(s, \cdot)$ has only one zero over $]0, 1[$. □

We study now the SPDE

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + \frac{c}{u^3} + W \\ u(t, 0) = u(t, 1) = a, \quad t \geq 0 \\ u(0, x) = u_0(x), \quad x \in [0, 1] \end{array} \right.$$

where $a \geq 0$ and $c > 0$ are fixed, $u_0 \in C([0, 1]) \cap K$ and we search for solutions $u \geq 0$.

Theorem

Let $a \geq 0$, $c > 0$ and $u_0 \in C([0, 1]) \cap K$. Then there exists a unique continuous $u : [0, +\infty[\times [0, 1] \mapsto [0, +\infty[$ such that

1. $u^{-3} \in L_{loc}^1([0, +\infty[\times]0, 1])$
2. A.s. for all $t \geq 0$ and $h \in C_c^\infty(0, 1)$

$$\begin{aligned} \langle u_t, h \rangle &= \langle u_0, h \rangle + \frac{1}{2} \int_0^t \langle u_s, h'' \rangle ds + \int_0^t \int_0^1 h(x) W(ds, dx) \\ &\quad + c \int_0^t \int_0^1 h(x) u^{-3}(s, x) ds dx. \end{aligned} \tag{30}$$

If $\delta > 3$ is such that $c = \frac{(\delta-3)(\delta-1)}{8}$, then the only invariant probability measure of (30) is $\mathbf{P}_{a,a}^\delta$.

The proof is based on the ideas we used in order to construct Bessel processes from SDEs with reflection. Let

$$\left\{ \begin{array}{l} \frac{\partial u^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 u^\varepsilon}{\partial x^2} + \frac{c}{(\varepsilon + u^\varepsilon)^3} + W + \eta^\varepsilon \\ u^\varepsilon(t, 0) = u^\varepsilon(t, 1) = a, \quad u^\varepsilon(0, x) = u_0(x) \\ u^\varepsilon \geq 0, \quad d\eta^\varepsilon \geq 0, \quad \int u^\varepsilon d\eta^\varepsilon = 0 \end{array} \right.$$

where $\varepsilon > 0$.

By monotonicity arguments, we see that $\varepsilon \mapsto u^\varepsilon$ is monotone non-increasing, while $\varepsilon \mapsto \varepsilon + u^\varepsilon$ is monotone non-decreasing.

Then, as $\varepsilon \downarrow 0$, u^ε converges uniformly to u and for all non-negative $h \in C([0, 1])$ and $t \geq 0$

$$\int_0^t \int_0^1 \frac{c}{(\varepsilon + u^\varepsilon(s, x))^3} h(x) \, dx \, ds \uparrow \int_0^t \int_0^1 \frac{c}{(u(s, x))^3} h(x) \, dx \, ds$$

as $\varepsilon \downarrow 0$. Moreover $\eta^\varepsilon \downarrow \eta$ and (u, η) solves

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + \frac{c}{u^3} + W + \eta \\ u(t, 0) = u(t, 1) = a, \quad u(0, x) = u_0(x) \\ u \geq 0, \quad d\eta \geq 0, \quad \int u \, d\eta = 0, \quad u^{-3} \in L^1_{loc} \end{cases}$$

We need to prove now that $\eta = 0$.

Note first that the invariant measure of u^ε is

$$\nu^{\varepsilon,a} := C(\varepsilon, a) \exp\left(-\frac{(\delta-1)(\delta-3)}{8} \int_0^1 \frac{1}{(\varepsilon + X_\tau)^2} d\tau\right) \mathbf{P}_{a,a}^3.$$

which converges to $\mathbf{P}_{a,a}^\delta$ as $\varepsilon \downarrow 0$. By the IbPF for $\varphi \equiv 1$

$$\begin{aligned} & \int \nu^{\varepsilon,a}(du_0) \mathbb{E} \left[\int_0^t \int_0^1 h(x) \eta^\varepsilon(ds, dx) \right] = \\ & = t C(\varepsilon, a) \int_0^1 dr h(r) \gamma(r, a) \int e^{2F_\varepsilon(\zeta)} \Sigma_a(r, d\zeta). \end{aligned}$$

Now for $r \in]0, 1[$ and $c = \frac{(\delta-1)(\delta-3)}{8} > 0$

$$\begin{aligned} & \int e^{2F_\varepsilon(\zeta)} \Sigma_a(r, d\zeta) = \\ & = \mathbf{E}_{a,a}^3 \left[\exp \left(-c \int_0^1 \frac{1}{(\varepsilon + X_\tau)^2} d\tau \right) \middle| X_r = 0 \right] \\ & \downarrow \mathbf{E}_{a,a}^3 \left[\exp \left(-c \int_0^1 \frac{1}{X_\tau^2} d\tau \right) \middle| X_r = 0 \right] = 0 \end{aligned}$$

by the law of the iterated logarithm or an explicit computation. \square

We have now functions $u = u^\delta$ for $\delta \geq 3$, stationary solutions to equations with reflection ($\delta = 3$) or repulsion from 0 ($\delta > 3$).

One of the main results of this course is the following

Theorem (Dalang, Mueller, Z.)

Let $\delta \geq 3$. If $k \in \mathbb{N}$ satisfies

$$k > \frac{4}{\delta - 2},$$

the probability that there exist $t > 0$ and $x_1, \dots, x_k \in [0, 1]$ such that $0 < x_1 < \dots < x_k < 1$ and $u(t, x_i) = 0$ for all $i = 1, \dots, k$, is zero.

Hitting of zero

In particular, setting for $\delta \geq 3$

$$\zeta(\delta) := \sup\{k : \exists (t, x_1, \dots, x_k) \in]0, 1[\times]0, 1[, u(t, x_i) = 0\}$$

then

- ▶ for $\delta = 3$, a.s. $\zeta(\delta) \leq 4$
- ▶ for $\delta \in]3, 3 + 1/3]$, a.s. $\zeta(\delta) \leq 3$
- ▶ for $\delta \in]3 + 1/3, 4]$, a.s. $\zeta(\delta) \leq 2$
- ▶ for $\delta \in]4, 6]$, a.s. $\zeta(\delta) \leq 1$
- ▶ for $\delta > 6$, a.s. $\zeta(\delta) = 0$.

In any case $\zeta(\delta) \leq 4$ a.s. for all $\delta \geq 3$. The behavior at the transition points $\delta \in \{3, 3 + 1/3, 4, 6\}$ might be non-optimal. Indeed, we conjecture that a.s.

$$\zeta(3) \leq 3, \quad \zeta(3 + 1/3) \leq 2, \quad \zeta(4) \leq 1, \quad \zeta(6) = 0.$$

Lemma

Let $\delta \geq 3$. For all $\beta \in (0, 1/2)$ and $T > 0$, there exists a finite random variable $\gamma \geq 0$ such that

$$|u(t, x) - u(t, y)| \leq \gamma |x - y|^\beta, \quad x, y \in [0, 1], T \geq t \geq 0,$$

and

$$u(t, x) - u(s, x) \geq -\gamma (t - s)^{\beta/2}, \quad T \geq t \geq s \geq 0, x \in [0, 1].$$

Proof of the Theorem

For all $\{q_i : i = 1, \dots, 2k\} \subset \mathbb{Q}$ with $0 < q_1 < \dots < q_{2k} < 1$, we define

$$Q := [0, 1] \times \prod_{i=1}^k [q_{2i-1}, q_{2i}]$$

and the random set

$$A := \{(t, x_1, \dots, x_k) \in Q : u(t, x_i) = 0, i = 1, \dots, k\}.$$

Then the claim follows if $\mathbb{P}(A \neq \emptyset) = 0$ for all such $(q_i)_i$.

Since $k > \frac{4}{\delta-2}$, we can fix $\alpha \in]0, 1[$ such that

$$4 + 2k - \alpha\delta k < 0.$$

For such α , we define the random set

$$A_n := \{(t, x_1, \dots, x_k) \in Q : u(t, x_i) \leq 2^{-\alpha n}, i = 1, \dots, k\}.$$

For all $n \in \mathbb{N}$, let

$$G_n := \{(j2^{-4n}, i_1 2^{-2n}, \dots, i_k 2^{-2n}) : j, i_1, \dots, i_k \in \mathbb{Z}\},$$

and consider the events

$$\mathcal{K}_n := \{A_n \cap G_n \neq \emptyset\}, \quad \mathcal{L}_n := \{A \neq \emptyset, A_n \cap G_n = \emptyset\}.$$

Since $A \subset A_n$ a.s.,

$$\{A \neq \emptyset\} \subseteq \mathcal{K}_n \cup \mathcal{L}_n.$$

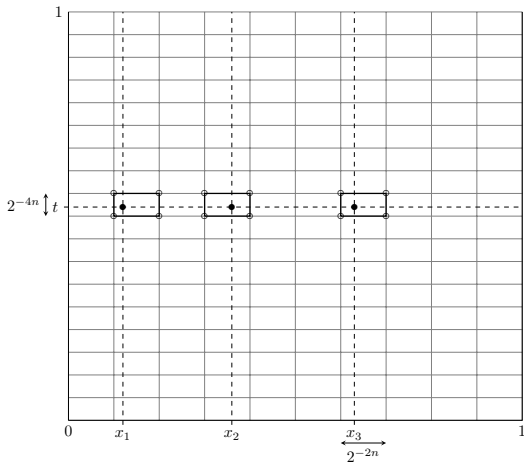


Figure : An element (t, x_1, x_2, x_3) of A with $k = 3$, namely $u(t, x_i) = 0$, $i = 1, 2, 3$. Either $u \leq 2^{-\alpha n}$ at k points $(s, y_1), \dots, (s, y_k) \in G_n$ (event \mathcal{K}_n) or u has a large oscillation in one of the three rectangles containing the (t, x_i) 's (event \mathcal{L}_n).

In order to prove that $\mathbb{P}(A \neq \emptyset) = 0$, we will show that the probabilities of \mathcal{K}_n and \mathcal{L}_n tend to 0 as $n \rightarrow \infty$.

Step 1. By definition, on the event \mathcal{L}_n , there exists $(t, x) \in [0, 1] \times]0, 1[$ such that $u(t, x) = 0$ but $A_n \cap G_n = \emptyset$. In particular, on \mathcal{L}_n , there exists $(s, y) \in G_n$ such that

$$u(s, y) > 2^{-\alpha n}, \quad 0 < t - s \leq 2^{-4n}, \quad |x - y| \leq 2^{-2n}.$$

Let $\beta \in]\alpha/2, 1/2[$. Then on \mathcal{L}_n

$$\begin{aligned} 2^{-\alpha n} < u(s, y) &= [u(s, y) - u(t, y)] + [u(t, y) - u(t, x)] \\ &\leq \gamma \left((t - s)^{\frac{\beta}{2}} + |y - x|^\beta \right) \leq \gamma 2^{-2\beta n + 1}. \end{aligned}$$

Therefore,

$$\mathbb{P}(\mathcal{L}_n) \leq \mathbb{P}(2^{-\alpha n} < \gamma 2^{-2\beta n + 1}) = \mathbb{P}(\gamma > 2^{(2\beta - \alpha)n - 1}) \rightarrow 0$$

as $n \rightarrow \infty$, since $2\beta > \alpha$ and γ is a.s. finite.

Step 2. We set $I_n := G_n \cap Q$. Then, by definition,

$$\mathbb{P}(\mathcal{K}_n) = \mathbb{P}(\exists(t, x_1, \dots, x_k) \in I_n : u(t, x_i) \leq 2^{-\alpha n}, i = 1, \dots, k).$$

Let $J_n := \{(x_1, \dots, x_k) : (0, x_1, \dots, x_k) \in I_n\}$. Then

$$\begin{aligned} \mathbb{P}(\mathcal{K}_n) &\leq \sum_{j=1}^{2^{4n}} \sum_{(x_1, \dots, x_k) \in J_n} \mathbb{P}(u(j2^{-4n}, x_i) \leq 2^{-\alpha n}, i = 1, \dots, k) \\ &= 2^{4n} \sum_{(x_1, \dots, x_k) \in J_n} \mathbf{P}_{a,a}^\delta(X_{x_i} \leq 2^{-\alpha n}, i = 1, \dots, k), \end{aligned} \tag{31}$$

since we have chosen u to be stationary and therefore, for any $t \geq 0$, u_t has distribution $\mathbf{P}_{a,a}^\delta$.

For $\epsilon > 0$ and $x_0 := 0, y_0 := a$

$$\begin{aligned} & \mathbf{P}_{a,a}^\delta (X_{x_i} \leq \epsilon, i = 1, \dots, k) \\ &= \int_{[0,\epsilon]^k} \left[\prod_{i=1}^k p_{x_i - x_{i-1}}(y_{i-1}, y_i) \right] \frac{p_{1-x_k}(y_k, a)}{p_1(a, a)} dy_1 \cdots dy_k, \end{aligned}$$

Since $p_t^\delta(x, y) \leq K y^{\delta-1}$, for all $(x_i)_{i=1,\dots,k} \in J_n$

$$\mathbf{P}_{a,a}^\delta (X_{x_i} \leq \epsilon, i = 1, \dots, k) \leq C \left[\int_0^\epsilon y^{\delta-1} dy \right]^k \leq C \epsilon^{\delta k}, \quad \epsilon > 0.$$

Therefore, by (31), since J_n has at most 2^{2kn} elements

$$\mathbb{P}(\mathcal{K}_n) \leq C 2^{4n} 2^{2kn} (2^{-\alpha n})^{\delta k} = C 2^{(4+2k-\alpha\delta k)n} \longrightarrow 0$$

as $n \rightarrow \infty$.



Theorem (Dalang, Mueller, Z.)

- (a) For all $\delta \in [3, 5]$, with positive probability, there exist $t > 0$ and $x \in (0, 1)$ such that $u_t(x) = 0$.
- (b) For $\delta = 3$, with positive probability there exist $t > 0$ and $\{x_1, x_2, x_3\} \subset (0, 1)$, $x_1 < x_2 < x_3$, such that $u_t(x_i) = 0$, $i = 1, 2, 3$.

We conjecture that

1. $\zeta(\delta) < \frac{4}{\delta - 2}$ a.s. for all $\delta \geq 3$.
2. $\mathbb{P}(\zeta(\delta) = 1) > 0$ for $\delta \in [4, 6)$, $\mathbb{P}(\zeta(\delta) = 2) > 0$ for $\delta \in [10/3, 4)$, and $\mathbb{P}(\zeta(\delta) = 3) > 0$ for $\delta \in [3, 10/3)$.

Integration by parts and Bessel processes

For $\delta = 1$ we have for all $\varphi \in C_c^1(\mathbb{R})$

$$\int_{\mathbb{R}_+} \varphi'(x) dx = -\varphi(0).$$

The associated dynamics is

$$\left\{ \begin{array}{l} \rho_t = x + B_t + \ell_t, \quad \rho_0 = x, \quad \ell_0 = 0, \\ \rho_t \geq 0, \quad d\ell_t \geq 0, \quad \int_0^\infty \rho_t d\ell_t = 0. \end{array} \right.$$

Integration by parts and Bessel processes

For $\delta > 1$ we have for all $\varphi \in C_c^1(\mathbb{R})$

$$\int_{\mathbb{R}_+} \varphi'(x) x^{\delta-1} dx = - \int_{\mathbb{R}} \varphi(x) \frac{\delta-1}{x} x^{\delta-1} dx.$$

The associated dynamics is

$$\rho_t = x + \frac{\delta-1}{2} \int_0^t \frac{1}{\rho_s} ds + B_t, \quad \rho_t \geq 0$$

limit as $\varepsilon \downarrow 0$ of

$$\rho_t^\varepsilon = x + \frac{\delta-1}{2} \int_0^t \frac{1}{\varepsilon + \rho_s^\varepsilon} ds + B_t + \ell_t^\varepsilon.$$

There is a family of local times ℓ^a defined by the occupation time formula

$$\int_0^t \phi(\rho_s) ds = \int_{\mathbb{R}_+} \phi(a) \ell_t^a a^{\delta-1} da.$$

Integration by parts and Bessel processes

For $\delta < 1$ we have for all $\varphi \in C_c^1(\mathbb{R})$

$$\int_{\mathbb{R}_+} \varphi'(x) x^{\delta-1} dx = - \int_{\mathbb{R}} (\varphi(x) - \varphi(0)) \frac{\delta-1}{x} x^{\delta-1} dx.$$

The associated dynamics is the limit as $\varepsilon \downarrow 0$ of

$$\rho_t^\varepsilon = x + \frac{\delta-1}{2} \int_0^t \frac{1}{\varepsilon + \rho_s^\varepsilon} ds + B_t + \ell_t^\varepsilon.$$

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$$\rho_t^\varepsilon = x + \frac{\delta-1}{2} \int_0^t \frac{1}{\varepsilon + \rho_s^\varepsilon} ds + B_t + \ell_t^\varepsilon.$$

The limit is equal to

$$\rho_t = \rho_0 + B_t + \frac{\delta-1}{2} \int_0^{+\infty} (\ell_t^a - \ell_t^0) a^{\delta-2} da$$

where the family of local times ℓ^a is defined by the occupation time formula

$$\int_0^t \phi(\rho_s) ds = \int_{\mathbb{R}_+} \phi(a) \ell_t^a a^{\delta-1} da.$$

Integration by parts and SPDEs

For $\delta = 3$ we have

$$\begin{aligned} \mathbf{P}_{a,a}^3 [\partial_h \varphi] &= -\mathbf{P}_{a,a}^3 [\varphi(X) \langle X, h'' \rangle] \\ &\quad - \int_0^1 dr h(r) \gamma(r, a) \mathbf{P}_{a,a}^3 [\varphi(X) | X_r = 0]. \end{aligned}$$

and the dynamics is

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + W + \eta \\ u(0, x) = u_0(x), \quad u(t, 0) = u(t, 1) = a \\ u \geq 0, \quad d\eta \geq 0, \quad \int u d\eta = 0 \end{array} \right.$$

Theorem

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3. There exists a family of local times $(\ell^a(\cdot, x))_{a \in [0, \infty), x \in (0, 1)}$, of u such that for all bounded Borel $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}$:

$$\int_0^t \varphi(u(s, x)) ds = \int_0^\infty \varphi(a) \ell^a(t, x) a^2 da, \quad t \geq 0.$$

Theorem

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$$\int_0^t \varphi(u(s, x)) ds = \int_0^\infty \varphi(a) \ell^a(t, x) a^2 da, \quad t \geq 0.$$

4. For all $t \geq 0$: $\eta([0, t], x) = \frac{1}{4} \ell^0(t, x)$.

Integration by parts and SPDEs

For $\delta > 3$ we have

$$\begin{aligned}\mathbf{E}_{a,a}^\delta [\partial_h \varphi(X)] &= -\mathbf{E}_{a,a}^\delta [\varphi(X) \langle X, h'' \rangle] \\ &\quad - \frac{(\delta-1)(\delta-3)}{4} \mathbf{E}_{a,a}^\delta [\varphi(X) \langle X^{-3}, h \rangle].\end{aligned}$$

and the dynamics is

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + \frac{(\delta-1)(\delta-3)}{8} u^{-3} + W \\ u(0, x) = u_0(x), u(t, 0) = u(t, 1) = a \end{cases}$$

limit of

$$\frac{\partial u^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 u^\varepsilon}{\partial x^2} + \frac{(\delta-1)(\delta-3)}{8} (u^\varepsilon + \varepsilon)^{-3} + W + \eta^\varepsilon.$$

For $\delta \in [2, 3[$ we set

$$\frac{\partial u^\varepsilon}{\partial t} = \frac{1}{2} \frac{\partial^2 u^\varepsilon}{\partial x^2} + \frac{(\delta - 1)(\delta - 3)}{8} (u^\varepsilon + \varepsilon)^{-3} + W + \eta^\varepsilon.$$

and as $\varepsilon \downarrow 0$ we have again a renormalisation effect.

Open problems:

- ▶ IbPF ?
- ▶ dynamics ?

The non-linearity has the wrong sign.

$$\delta \in [2, 3[$$

$$\begin{aligned} \mathbf{E}_{a,a}^{\delta} [\partial_h \varphi(X)] &= -\mathbf{E}_{a,a}^{\delta} [\varphi(X) \langle X, h'' \rangle] \\ &- \kappa(\delta) \int_0^1 dr h(r) \int_0^{+\infty} \frac{p_r^{\delta}(a, c) p_{1-r}^{\delta}(c, a)}{p_1^{\delta}(a, a)} \cdot \\ &\cdot \frac{1}{c^3} \left[\mathbf{E}_{a,a}^{\delta}(\varphi(X) | X_r = c) - \mathbf{E}_{a,a}^{\delta}(\varphi(X) | X_r = 0) \right] c^{\delta-1} dc \end{aligned}$$

$$\delta \in [2, 3[$$

$$\begin{aligned} \mathbf{E}_{a,a}^\delta [\partial_h \varphi(X)] &= -\mathbf{E}_{a,a}^\delta [\varphi(X) \langle X, h'' \rangle] \\ &- \kappa(\delta) \int_0^1 dr h(r) \int_0^{+\infty} \frac{p_r^\delta(a, c) p_{1-r}^\delta(c, a)}{p_1^\delta(a, a)} \cdot \\ &\cdot \frac{1}{c^3} \left[\mathbf{E}_{a,a}^\delta(\varphi(X) | X_r = c) - \mathbf{E}_{a,a}^\delta(\varphi(X) | X_r = 0) \right] c^{\delta-1} dc \end{aligned}$$

and the SPDE

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} = \frac{1}{2} \frac{\partial^2 u}{\partial x^2} + \frac{\partial}{\partial t} \frac{\kappa(\delta)}{2} \int_0^{+\infty} \frac{\ell^c(t, x) - \ell^0(t, x)}{c^3} c^{\delta-1} dc + W \\ u(t, 0) = u(t, 1) = a, \quad u(0, x) = u_0(x) \\ \int_0^t \psi(u(s, x)) ds = \int_0^{+\infty} \psi(c) \ell^c(t, x) c^{\delta-1} dc \end{array} \right.$$

Integration by parts and SPDEs

For $\delta < 2$ the situation is even more complicated since 0 is hit by the stationary profile.

The case $\delta = 1$ is the most intriguing since it is the limit of homogeneous pinning models.

There is an IbPF for $\delta = 1$ but the form of the dynamics is hard even to conjecture.