

Reflected Brownian motion in a cone and Martin boundary.

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- I. Reflected Brownian motion
 - A. The Brownian motion
 - B. Reflection of Brownian motion in dimension 1
 - C. The two-dimensional reflected Brownian motion
 - D. Condition for transience and recurrence
- II. Martin Boundary
 - A. Motivation
 - B. Construction and theorem
 - C. Harmonic function and Doob's transform
- III. Martin Boundary of Reflected Brownian Motion

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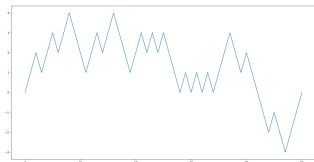
C. Harmonic function and Doob's transform

III. Martin Boundary of Reflected Brownian Motion

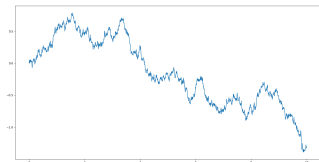
Motivation 1 of Brownian motion

Recall : Donsker's Theorem

Brownian Motion is the scale limit of random walks.



(a) Centered random walk (L^2)
(discrete time)



(b) Brownian motion (continuous time)

Motivation 2 of Brownian motion : Robert Brown the genius

Pollen grain on the water surface : does not have a C^1 trajectory !

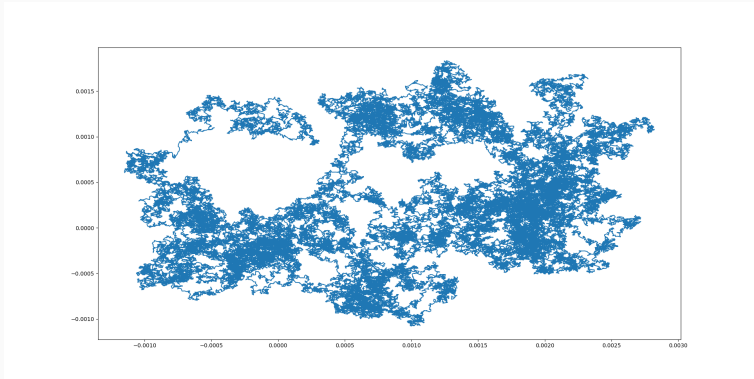


Figure 2 – Brownian motion dimension 2

Properties of Brownian motion

Proposition

A Brownian motion is (almost surely) everywhere **continuous** and **nowhere differentiable**.

Properties of Brownian motion

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A Brownian motion is (almost surely) everywhere **continuous** and **nowhere differentiable**.

Proposition

If $(B_t)_{t \geq 0}$ is a Brownian motion, then it is a **Markov process** : it **forgets the past**.

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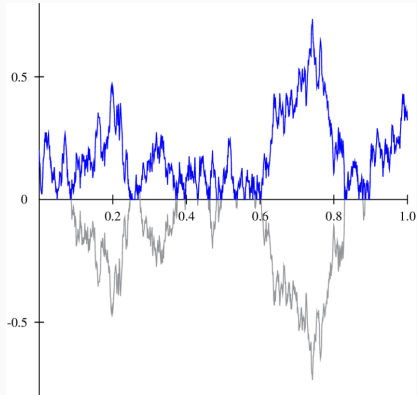
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Reflecting a Brownian motion : naive approach

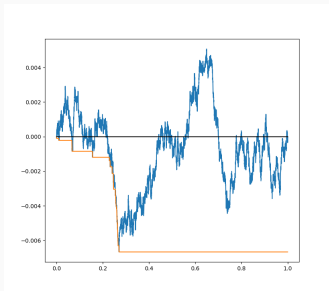
Naive approach : consider $(|B_t|)_{t \geq 0}$



(Source : Brownian Motions on Metric Graphs : Feller Brownian Motions on Intervals Revisited)

Reflecting a Brownian motion : local time approach

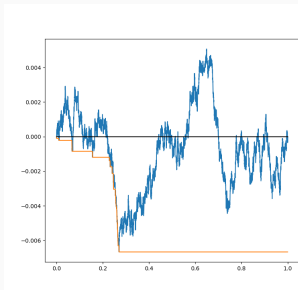
We define $L_t = -\min(B_s, 0 \leq s \leq t)$



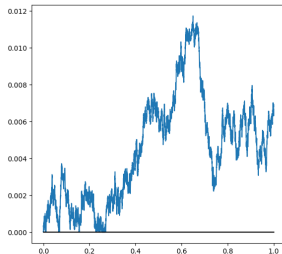
(a) $(B_t)_{t \geq 0}$, $(-L_t)_{t \geq 0}$

Reflecting a Brownian motion : local time approach

We define $L_t = -\min(B_s, 0 \leq s \leq t)$



(a) $(B_t)_{t \geq 0}$, $(-L_t)_{t \geq 0}$

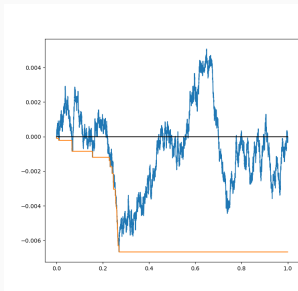


(b) $(B_t + L_t)_{t \geq 0}$ is a **RBM**

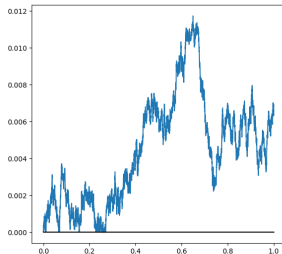
$(L_t)_{t \geq 0}$ is called the **local time** of the reflected Brownian motion at 0 : it is a **pushing process**.

Reflecting a Brownian motion : local time approach

We define $L_t = -\min(B_s, 0 \leq s \leq t)$



(a) $(B_t)_{t \geq 0}$, $(-L_t)_{t \geq 0}$



(b) $(B_t + L_t)_{t \geq 0}$ is a **RBM**

$(L_t)_{t \geq 0}$ is called the **local time** of the reflected Brownian motion at 0 : it is a **pushing process**.

Theorem : Tanaka formula

$$|W_t| = B_t + L_t$$

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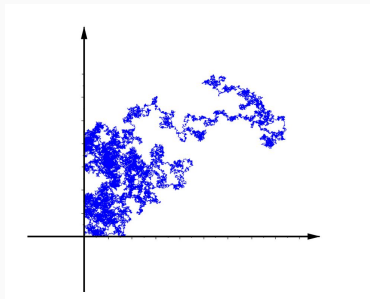
B. Construction and theorem

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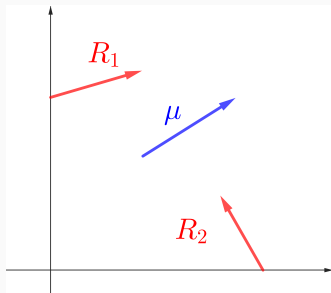
III. Martin Boundary of Reflected Brownian Motion

What is it ?

Reflected Brownian motion in \mathbb{R}_+^2 : $Z_t = z_0 + B_t + \mu t + RL_t$



(a) Exemple de trajectoire



(b) Drift, Vecteurs de réflexion

- $(B_t)_{t \geq 0}$ is a Brownian motion, $\mu \in \mathbb{R}^2$ is the drift
- $R = (R_1, R_2)$ reflection matrix
- $(L_t)_{t \geq 0}$ local time on the axes $\text{supp}(dL^i) \subset \{t, Z_t^i = 0\}$.

Existence and uniqueness

Theorem : Weak existence and uniqueness

Existence and uniqueness in law at all positive times if and only if

$$r_{11} > 0, r_{22} > 0, \text{ and } [\det(R) > 0 \text{ or } r_{21}, r_{12} > 0].$$

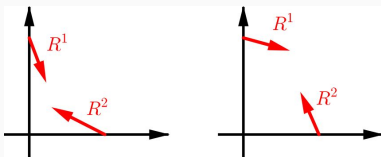


Figure 6 – Not defined

Defined for all time

Existence and uniqueness

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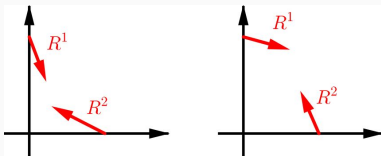


Figure 6 – Not defined Defined for all time

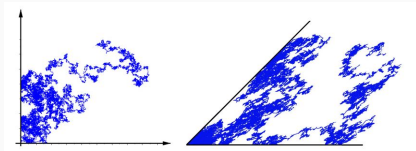


Figure 7 – From quadrant to cone : linear transformation

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Definition : Recurrent or Transient process

A Markov process is **recurrent** if it comes back almost surely in any open set. Otherwise, such a process is called **transient**.

Example :

- Drifted Brownian motion $(B_t + \mu t)_{t \geq 0}$ ($\mu \neq 0$) is transient in \mathbb{R}^d
- Brownian motion in dimension $d \geq 3$ is transient in \mathbb{R}^d

Recurrence and transience : competition drift/reflection

Theorem : Conditions for transience (Hobson-Rogers, 1993)

$(Z_t)_{t \geq 0}$ is transient if and only if

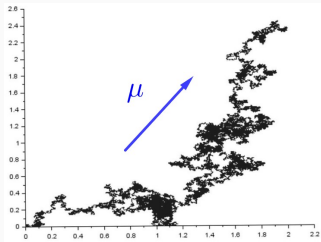
$$r_{11}\mu_1 - r_{21}\mu_2^- \geq 0 \quad \text{or} \quad r_{12}\mu_1^- - r_{22}\mu_2 \leq 0.$$

Recurrence and transience : competition drift/reflection

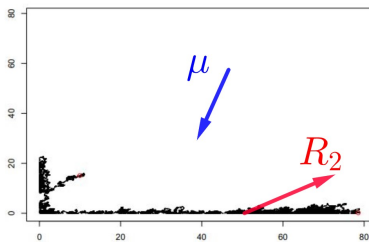
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(a) Example where $\mu_1, \mu_2 > 0$.

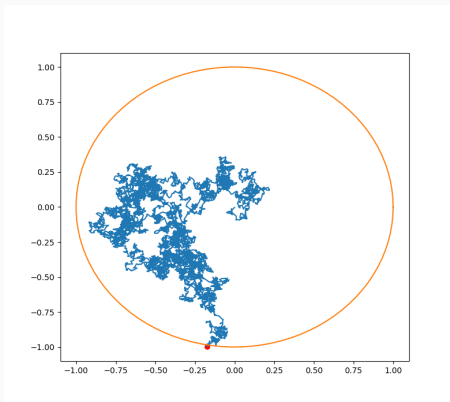


(b) Escape along an axis

Assuming μ points outward : Z is transient.

A last example

- Brownian motion in a ball killed when it reaches $\partial D(0, 1)$



Motivation

(One) motivation for transient processes : is it possible to define a "limit at infinity" ?

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Boundary value problem and harmonic functions

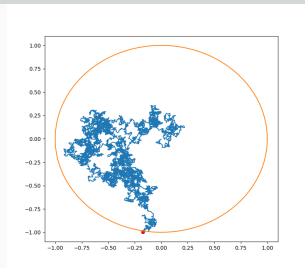
$$\begin{cases} \Delta h = 0 \\ h|_{\partial D} = f \in C(\partial D) \end{cases}$$

(a) Analytic problem

Boundary value problem and harmonic functions

$$\begin{cases} \Delta h = 0 \\ h|_{\partial D} = f \in C(\partial D) \end{cases}$$

(a) Analytic problem



(b) Probabilistic interpretation

Theorem : Harmonic functions

If B is a Brownian motion and D is a smooth bounded domain, $h(z) := \mathbb{E}_z[f(B_T)]$ is a solution where $T = \inf(t \geq 0, B_t \in \partial D)$.

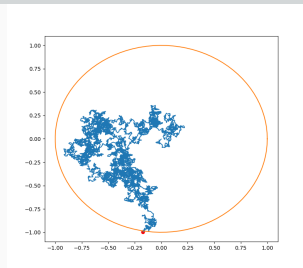
In particular,
$$h(z) = \int_{\partial D} f(u)k(z, u)du$$

where $k(z, u)du = P_z(B_T \in du)$

Boundary value problem and harmonic functions

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Motivation : find harmonic functions with stochastic approach

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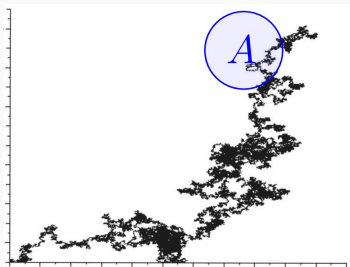
Green's measure

Let be $(B_t)_{t \geq 0}$ a transient Brownian motion (or transient process).

Definition : / Proposition : Green measure from z_0

The following measure has a density $g(z_0, \cdot)$ inside the cone :

$$G(z_0, A) := \mathbb{E}_{z_0} \left[\int_0^\infty \mathbf{1}_A(B_t) dt \right] = \iint_A g(z_0, z) dz$$



(a) Time passed in A .

Definition : Harmonic functions

A function h is harmonic for a Markov process $(Z_t)_{t \geq 0}$ if for all z ,

$$\mathbb{E}_z[h(Z_t)] = h(z).$$

Example :

This is equivalent with $\Delta h = 0$ for $(Z_t)_{t \geq 0}$ Brownian motion.

Proposition

For $z_0 \in \mathbb{R}^d$, $g(\cdot, y)$ is harmonic on $\mathbb{R}^d \setminus \{y\}$

Martin Kernel and construction

Definition : Martin Kernel and metric

Fix z_0 in \mathbb{R}^d . For $x, y \in \mathbb{R}^d$, define

$$k(x, y) = \begin{cases} \frac{g(x, y)}{g(z_0, y)} & \text{if } y \neq z_0 \\ 0 & \text{if } y = z_0. \end{cases} \quad (1)$$

Then, the following expression defines a metric on \mathbb{R}^d :

$$\rho(z_1, z_2) = \int_{\mathbb{R}^d} \frac{|k(x, z_1) - k(x, z_2)|}{1 + |k(x, z_1) - k(x, z_2)|} e^{-|x|^2} dx. \quad (2)$$

Remark

We recognize a "pointwise convergence topology" for the family $(k(x, \cdot))_{x \in \mathbb{R}^d}$.

Martin Boundary

Definition : Martin Boundary

Define Γ as $\Gamma = \{(x_n)_{n \geq 0}, (k(\cdot, x_n))_n \text{ converges pointwise}\} / \sim$
where \sim is the equivalent relation characterising the limit of $(k(\cdot, x_n))_n$

Theorem : Martin compactification

The metric ρ extends naturally to $\mathbb{R}^d \cup \Gamma$. Furthermore,

- $k(\cdot, \xi) = k(\cdot, \eta) \implies \eta = \xi$.
- $\mathbb{R}^d \cup \Gamma$ is **compact** under ρ .
- $y_n \xrightarrow[n \rightarrow \infty]{} \eta \in \Gamma \iff k(\cdot, y_n) \xrightarrow[n \rightarrow \infty]{} k(\cdot, \eta)$ pointwise.

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Proposition

For $\eta \in \Gamma$, $k(\cdot, \eta)$ is harmonic on \mathbb{R}^d .

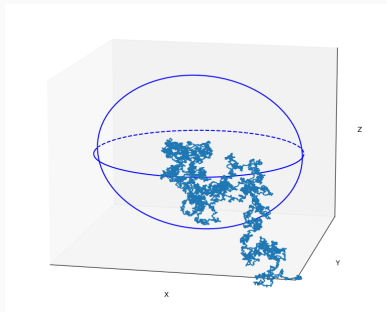
Limit at infinity

Theorem : Limit at infinity

Almost surely, $B_t \xrightarrow[t \rightarrow \infty]{} B_\infty \in \Gamma$

Example :

Martin Boundary of **drifted** Brownian Motion : $\Gamma \sim \mathbb{S}^{d-1}$



Remark

The Martin Boundary see more than the limit at infinity

Representation of nonnegative harmonic functions

Theorem : Representation of nonnegative harmonic function

Let $h \geq 0$ be a harmonic function. Then, there is a Radon measure μ_h on Γ satisfying

$$h(z) = \int_{\Gamma} k(z, \eta) d\mu_h(\eta). \quad (3)$$

Furthermore, every function defined by (3) is harmonic.

Example :

For the killed Brownian motion at $\partial D(0, 1)$,

- $\Gamma = \partial D(0, 1)$
- μ_h is the boundary condition

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Remark

It works only for **nonnegative** harmonic function

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Theorem : Doob Transform

If h is nonnegative harmonic, then $P^h(A) = \mathbb{E} \left[\frac{h(Z_t)}{h(Z_0)} \mathbf{1}_A \right]$ defines a probability under which $(Z_t)_{t \geq 0}$ remains a Markov process.

Harmonic functions

Theorem : Doob Transform

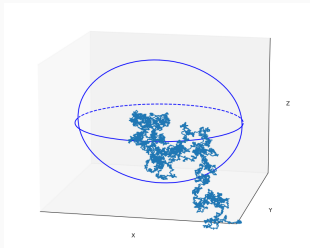
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Proposition

If Γ is minimal, for all $\eta \in \Gamma$, $P_x^{k(\cdot, \eta)}(X_\infty = \eta) = 1$.

Example :

For $u \in \mathbb{S}^{d-1}$, [Condition by $k(\cdot, u)$] = [Converge in direction u]



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Reflected Brownian motion in a cone

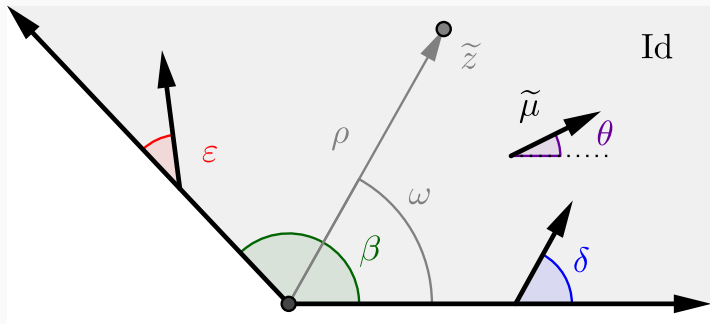


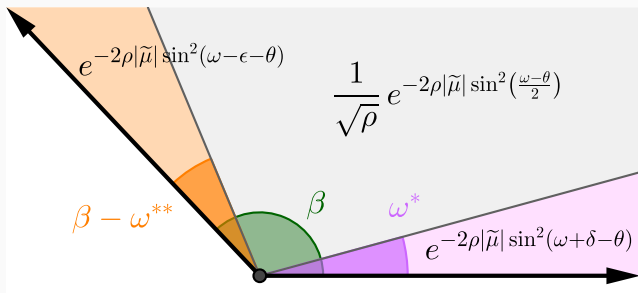
Figure 10 – Notations in the cone

Theorem

Theorem : Asymptotics of the Green's Density

Let $\omega^* = \theta - 2\delta$ and $\omega^{**} = \theta + 2\varepsilon$. We have the asymptotics for $g^{(z_0)}(\rho \cos(\omega), \rho \sin(\omega))$, $\rho \rightarrow \infty$, $\omega \rightarrow \omega_0 \notin \{0, \omega^*, \omega^{**}, \beta\}$:

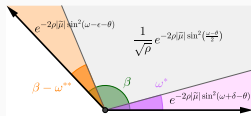
$$g^{(z_0)}(\rho \cos(\omega), \rho \sin(\omega)) \sim \dots$$



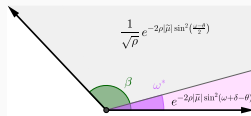
(a) $0 < \omega^* < \omega^{**} < \beta$

Remarks

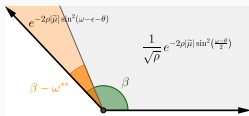
- According to the angles of the parameters, we have 4 configurations



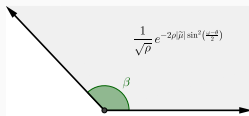
(a) $0 < \omega^* < \omega^{**} < \beta$



(b) $0 < \omega^* < \beta < \omega^{**}$



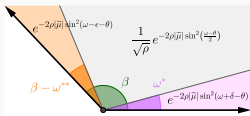
(c) $\omega^* < 0 < \omega^{**} < \beta$



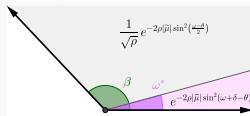
(d) $\omega^* < 0 < \beta < \omega^{**}$

Remarks

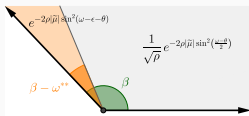
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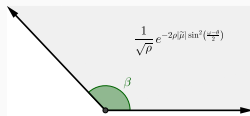
(a) $0 < \omega^* < \omega^{**} < \beta$



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(c) $\omega^* < 0 < \omega^{**} < \beta$



(d) $\omega^* < 0 < \beta < \omega^{**}$

- Asymptotic expansion (middle zone :)

$$g(\rho \cos \omega, \rho \sin \omega) \underset{\substack{\rho \rightarrow \infty \\ \omega \rightarrow \omega_0}}{\sim} e^{-2\rho|\mu| \sin^2(\frac{\omega - \theta}{2})} \frac{1}{\sqrt{\rho}} \sum_{k=0}^n \frac{c_k(\omega)}{\rho^k}$$

We consider the \mathbb{R}_+^2 quadrant.

- ▷ Definition of Green measures on the boundaries
- ▷ Laplace transforms, **functional equation** and extension of Laplace transforms
- ▷ **Laplace inversion**
- ▷ Residue theorem
- ▷ **Saddle point method**

Corresponding Martin Boundary

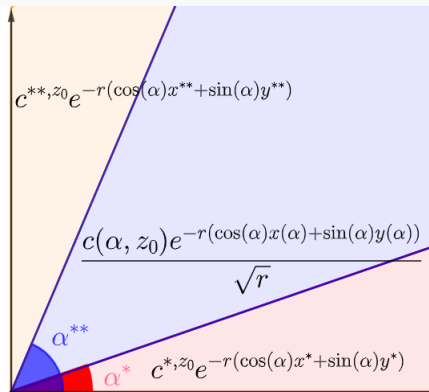


Figure 13 – Asymptotics of $g^{(z_0)}(r \cos(\alpha), r \sin(\alpha))$ as $r \rightarrow \infty$

Remark

Constants $c(\alpha, z_0)$ are the harmonic functions $k(z_0, \alpha)$ relative to Martin kernel

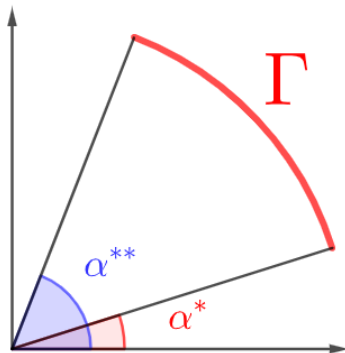


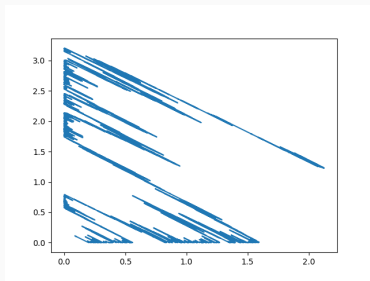
Figure 14 – Shape of Martin Boundary of the process : $\Gamma = [\alpha^*, \alpha^{**}]$

Degenerate Model - Link to particles ?

Three particles $X_1 \leq X_2 \leq X_3$ colliding with each other, and the middle one is a Brownian motion : **gapping process**
($X_3 - X_2, X_2 - X_1$) is a reflected Brownian motion.



(a) System of 3 particles
(Karatzas Ichiba paper)



(b) Degenerate reflected Brownian motion

Thank you for listening!

References and existence

- Survey : SRBM in the orthant - Williams (1995)
- Existence and uniqueness of semimartingale reflecting Brownian motions in an orthant - Taylor and Williams (1992)
- Other...
- Tomoyuki Ichiba, Ioannis Karatzas - Degenerate Competing Three-Particle Systems (2021)